MOS-AK workshop
13 Dec. 2008

Sizing CMOS circuits by means of the g_m/I_D methodology and a compact model.

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sizing....

find D.C. currents and transistor sizes meeting :

- a prescribed gain-bandwidth product
- minimal power consumption
- minimal area
- large gain
- ....

low- voltage, low-power MOS circuits

Outline

Sizing...

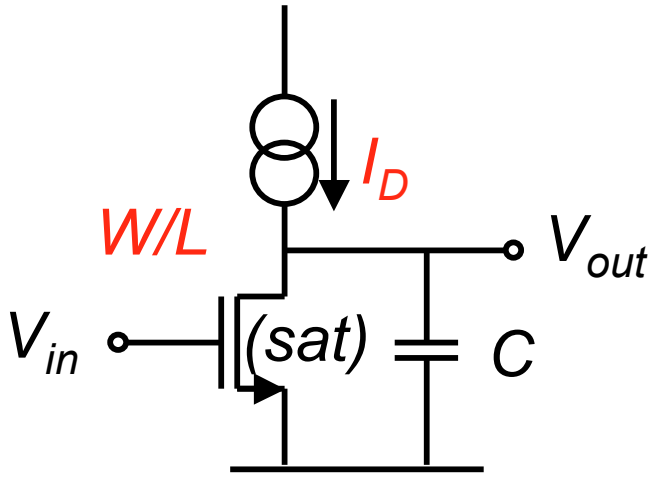
- the Intrinsic Gain Stage (I.G.S.)
  - g_m/I_D semi-empirical methodology
  - g_m/I_D compact model methodology
  - L-V, L-P, short channel I.G.S.
- the Miller Op. Amp.

Conclusion

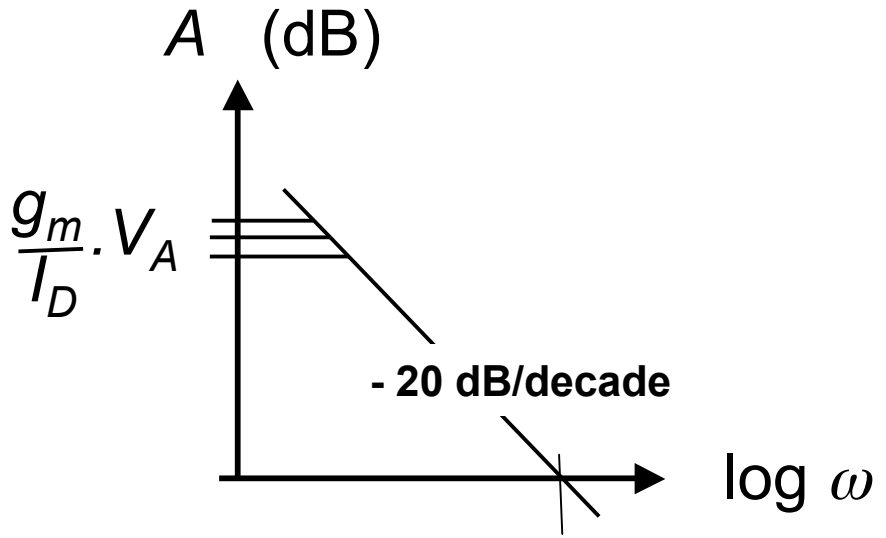
The Intrinsic Gain Stage (I.G.S.)

gain-bandwidth sizing:

find I_D and W/L
achieving ω_T

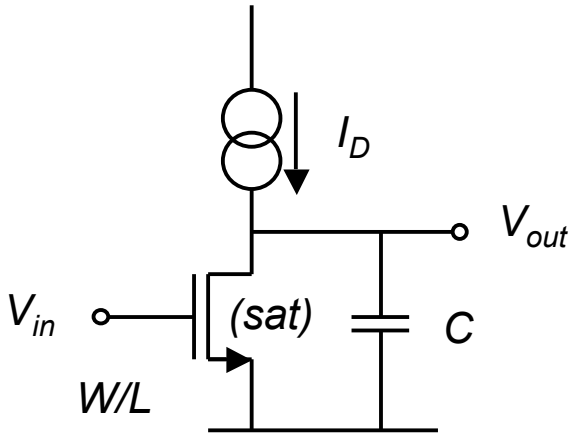


$$g_m = \omega_T . C$$



$$\omega_T = \frac{g_m}{C}$$

1) (strong inversion)



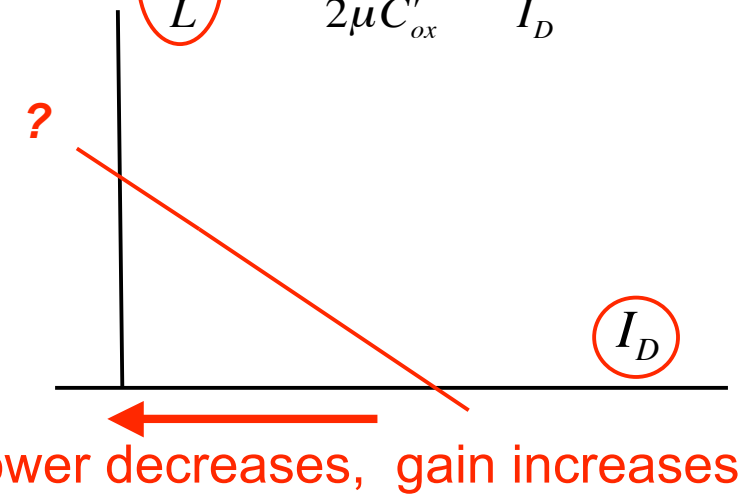
$$\beta = \mu C'_{ox} \frac{W}{L}$$

$$g_m = \frac{\partial I_D}{\partial V_G} = \sqrt{\frac{2\beta I_D}{n}}$$

$$g_m = \omega_T C$$

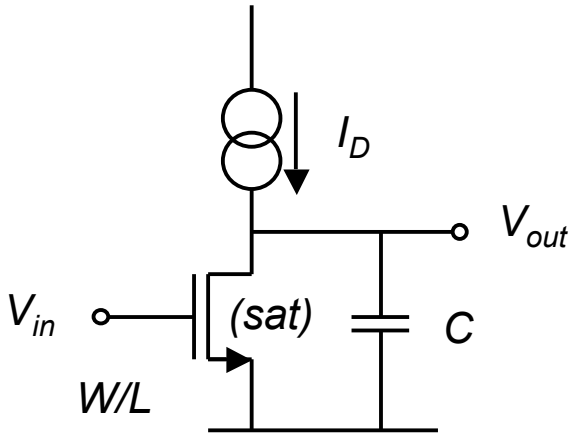
$$\frac{W}{L} = \frac{n\left(\omega_T C\right)^2}{2\mu C'_{ox}} \cdot \frac{1}{I_D}$$

$$A = \frac{g_m}{I_D} V_A = \sqrt{\frac{2\beta}{n I_D}} V_A$$



power decreases, gain increases

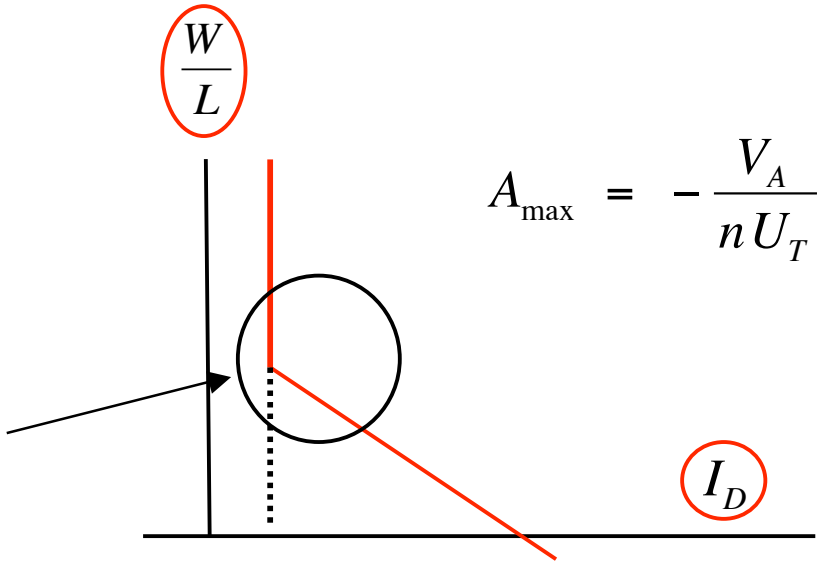
2) weak inversion)



$$I_D = I_o \exp\left(\frac{V_G}{nU_T}\right)$$

$$g_m = \frac{I_D}{nU_T}$$

$$g_m = \omega_T C$$



$$A_{\max} = -\frac{V_A}{nU_T}$$

sizing in moderate inversion?

$$I_D = nU_T\omega_T C$$

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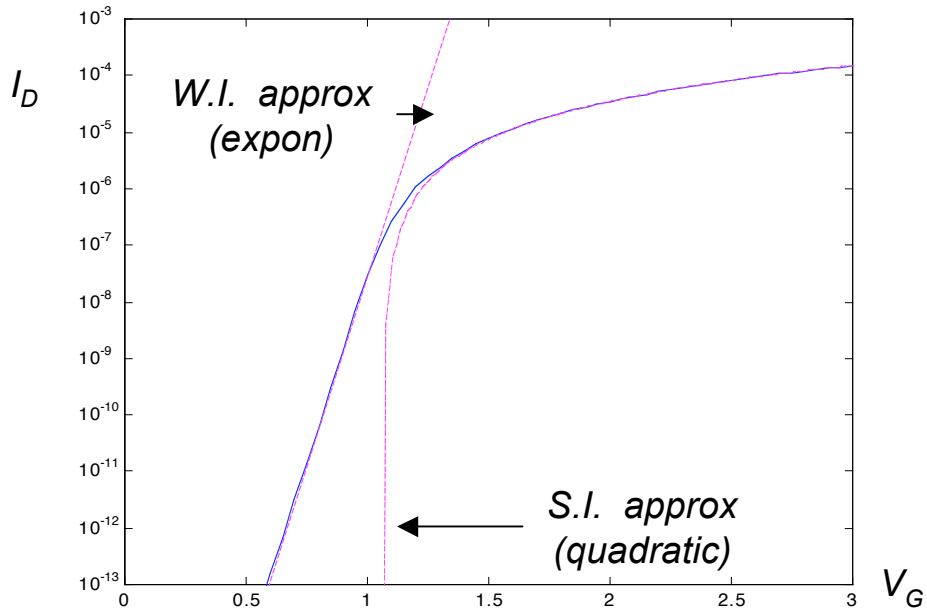
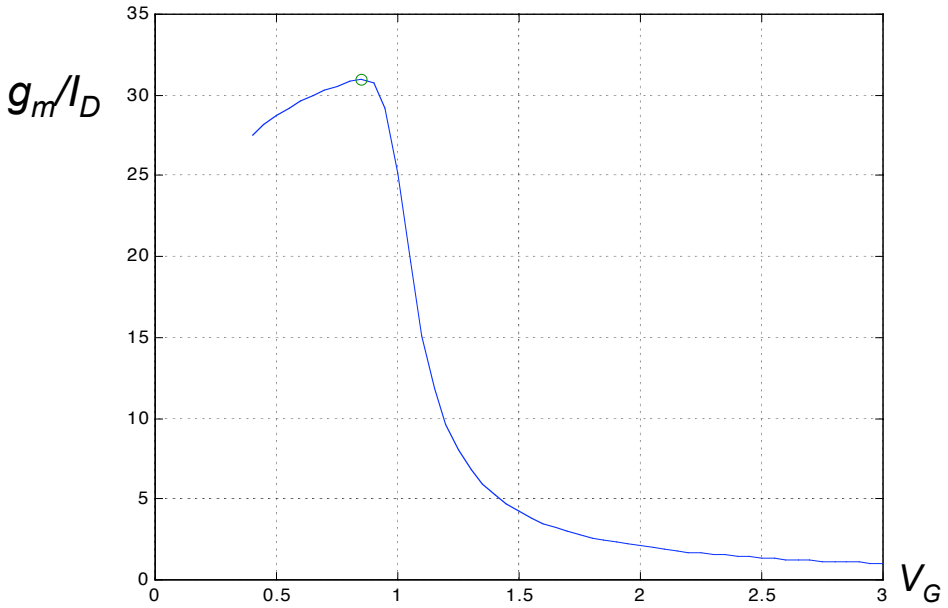
Conclusion

what does g_m/I_D represent ?

$$\left(\frac{g_m}{I_D}\right) = \frac{1}{I_D}\frac{\partial I_D}{\partial V_{GS}} = \frac{\partial}{\partial V_{GS}}\log\left(I_D\right)$$





why g_m/I_D?

- g_m/I_D does not depend on the transistor width
  g_m and I_D are proportional to W

- g_m/I_D bridges a small signal and a large signal quantity

$$g_m \quad \Leftrightarrow \quad I_D$$

- g_m/I_D controls gain, power consumption ...

$$A = \frac{g_m}{I_D} V_A$$

The g_m/I_D sizing methodology (semi-empirical)

- **measurements**
- **reconstructed data (BSIM, PSP...)**
- **model E.K.V...**

$$g_m = \omega_T C$$

$$I_D(V_{GS}) = \frac{g_m}{\left(\frac{g_m}{I_D}\right)}$$

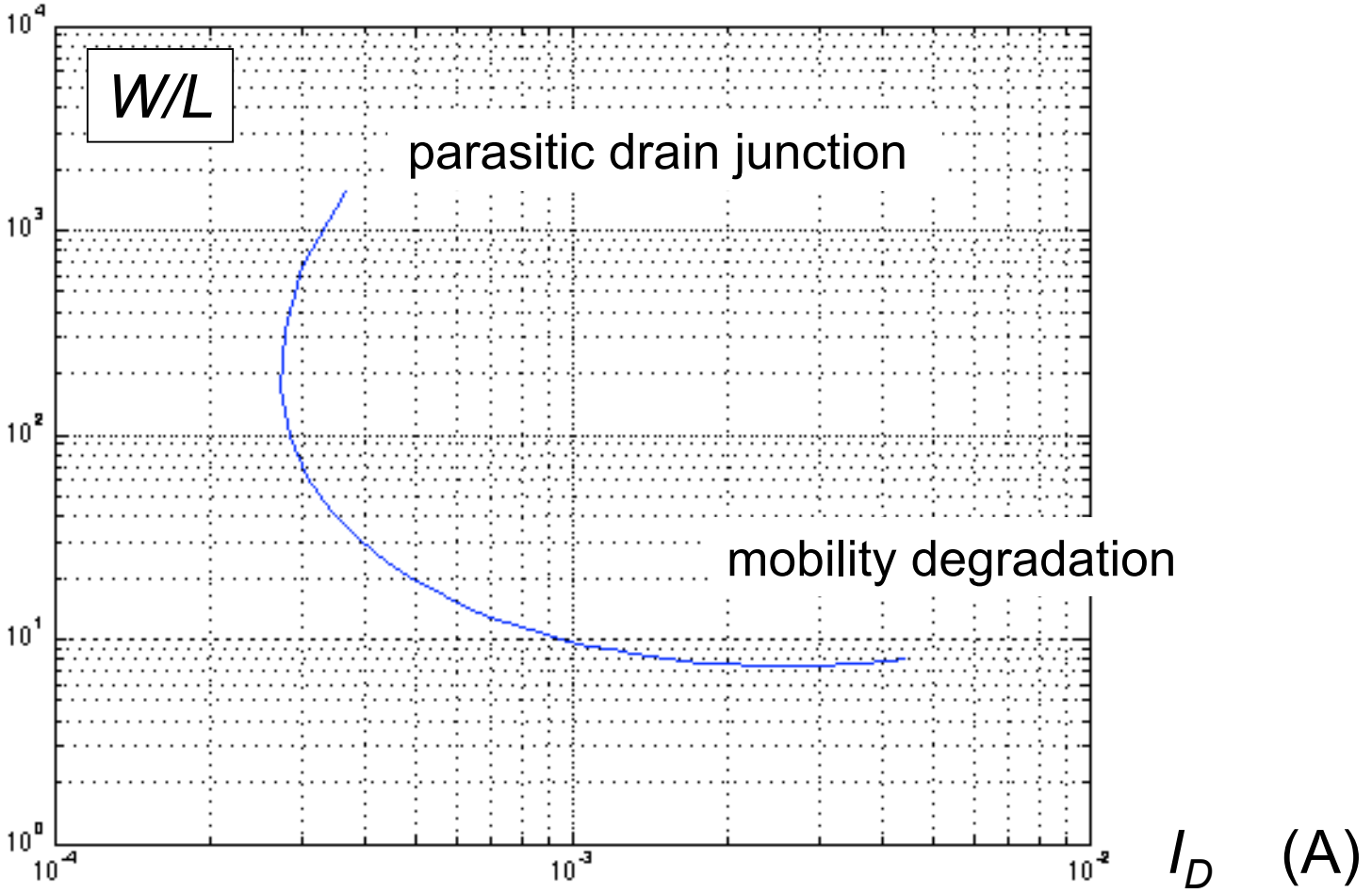
$$W(V_{GS}) = \frac{I_D(V_{GS})}{I_{D\,ref}(V_{GS})}(W)_{ref}$$

$$\frac{\partial}{\partial V_{GS}}\log\left(I_{Dref}(V_{GS})\right)$$

W_{ref}

monitors the mode of operation of the MOS transistor

Example



f_T = 1 GHz; C_o = 1 pf; L = 120 nm; V_S = 0; V_{DS} = 0.6 V; Wmax = 1 µm;

First paper

A g_m/I_D Based Methodology for the Design of CMOS Analog Circuits and Its Application to the Synthesis of a Silicon-on-Insulator Micropower OTA

F. Silveira, D. Flandre, P.G.A. Jespers

IEEE JOURNAL OF SOLID STATE CIRCUITS, VOL. 31, NO. 9, SEPTEMBER 1996
p. 1314 ...

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The ACM and EKV compact models

+ *continuous model (saturation, weak to strong inversion)*
+ *few parameters:*
  - *n subthreshold slope factor*
  - *I_{Su} unary specific current*
  - *V_{To} threshold voltage*
- *uniformly doped substrate, no mobility degradation,*
- *gradual channel approximation (1D)*

A.C.M.

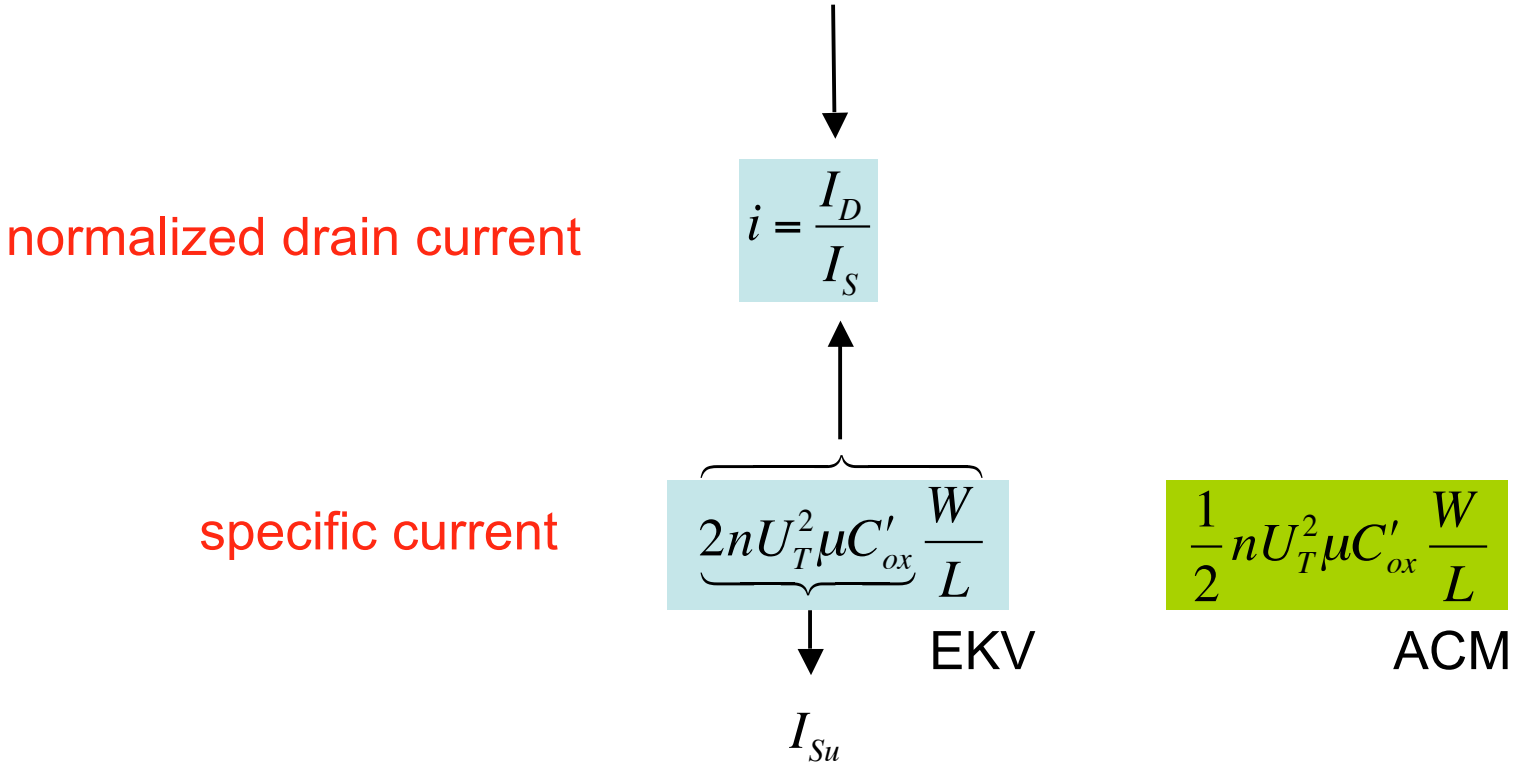
- An MOS transistor model for analog circuit design
  Ana I. Cunha, M.C. Schneider, C. G. Montoro.
  IEEE JSSC,vol 33,n°10,oct, 1998.

E.K.V.

- An analytical MOS transistor model valid in all regions of operation and dedicated to Low-Voltage and Low-current applications.
  Chr. C.Enz, F. Krummenacher, E. A. Vittoz.
  Analog Integrated Circuits and Signal Processing, Kluwer Ac. Publ. 1995.

The compact model (1)

drain current normalization



unary specific current ($W = L$)

The compact model (2)

norm. drain current (*saturation*)

$$i = q^2 + q$$

normalized mobile charge density

$$q = -\frac{Q'_i}{2nU_T C'_{ox}}$$

channel voltage

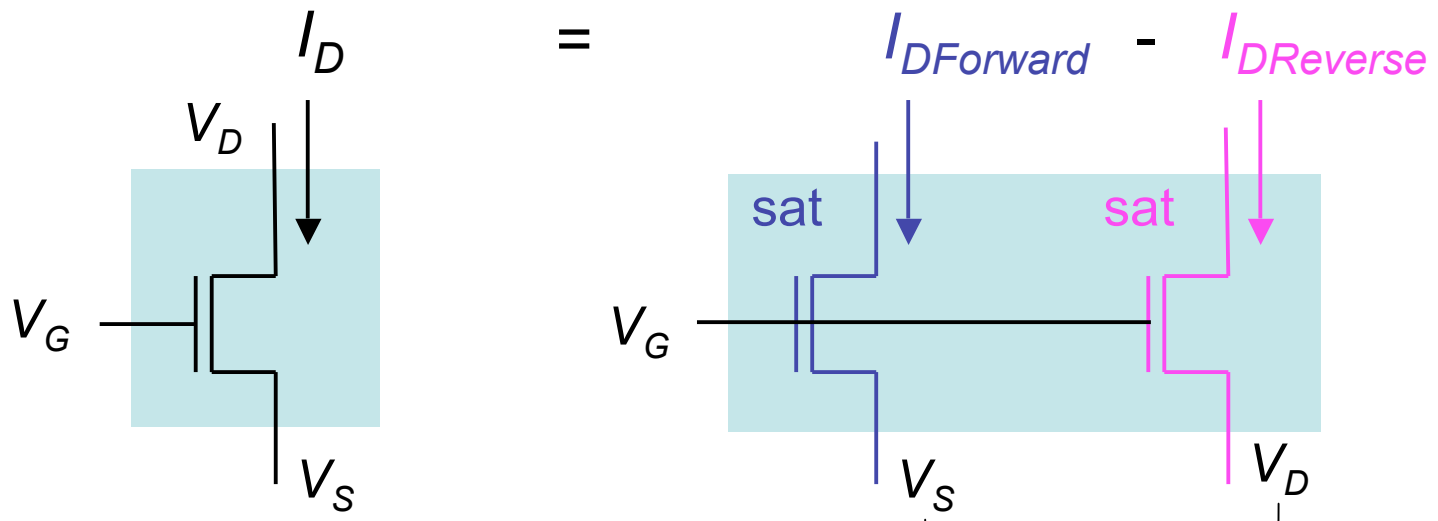
$$V_P - V = U_T\left[2(q-1) + \log(q)\right]$$

pinch - off voltage

gate voltage

$$V_P = \frac{V_G - V_{To}}{n}$$

The compact model (3)



$$V_P - V_S = U_T\left[2\left(q_F - 1\right) + \log\left(q_F\right)\right]$$

$$V_P - V_D = U_T\left[2\left(q_R - 1\right) + \log\left(q_R\right)\right]$$

$$i = q_F^2 + q_F - \left(q_R^2 + q_R\right)$$

example : $I_{Du}(V_G)$ of grounded source (V_S = *0* V) saturated (q => q_F) transistor

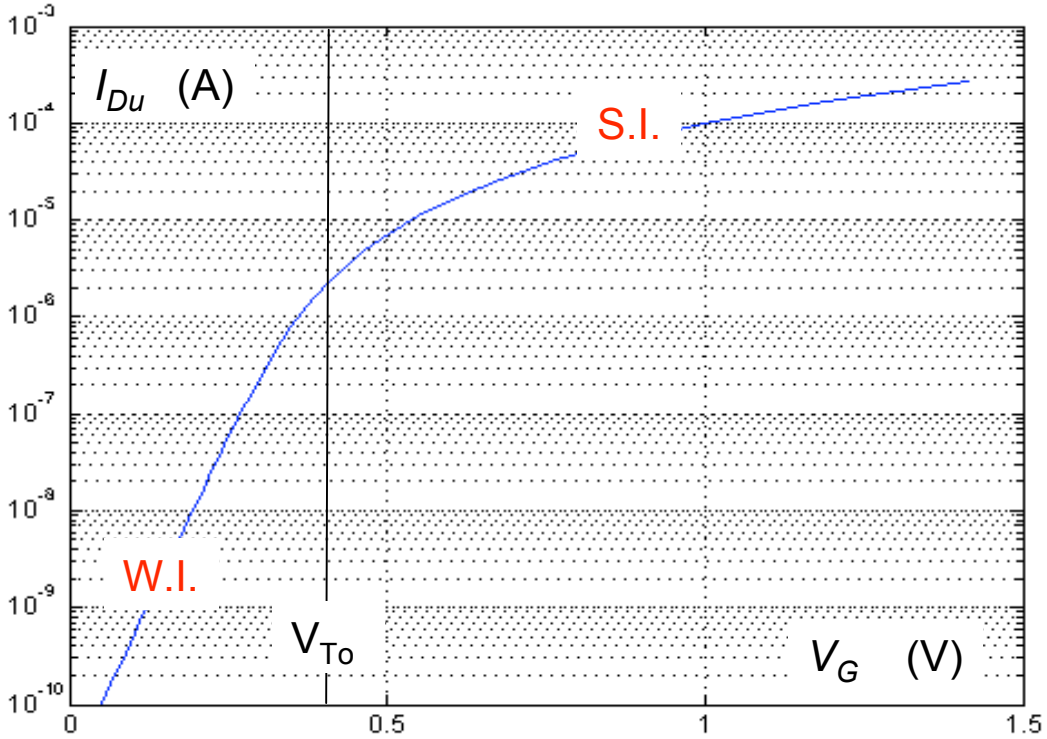
parametric method

$$q_F \begin{cases} i = q_F^2 + q_F & \Longrightarrow \quad I_{Du} = i\,I_{Su} \\ V_P = U_T\left(2(q_F - 1) + \log q_F\right) & \Longrightarrow \quad V_G = nV_P + V_{To} \end{cases}$$

```
% data
UT  = .026;
n   = 1.2;
Isu  = 1e-6;
VTo = 0.4;

% compute
qF  = logspace(-4,1.2,50);
i   = qF.^2 + qF;
ID  = i*Isu;
VP = UT*(2*(qF-1) + log(qF));
VG = n*VP + VTo;

% plot
semilogy(VG,ID); grid
```



g_m/I_D of the saturated transistor

$$\frac{g_m}{I_D} = \frac{d\log(i)}{dV_G}$$

$$\begin{cases} d\log(i) = \dfrac{di}{i} = \dfrac{2q_F + 1}{i}\, dq_F \\ and \\ dV_G = n\, dV_P = nU_T \left(2 + \dfrac{1}{q_F}\right) dq_F = nU_T\, \dfrac{2q_F + 1}{q_F}\, dq_F \end{cases}$$

$$\frac{g_m}{I_D} = \frac{1}{nU_T}\,\frac{q_F}{i} = \frac{1}{nU_T}\,\frac{1}{q_F + 1}$$

sizing the Intrinsic Gain Stage by means of the E.K.V. model

E.K.V. param

g_m/I_D sizing

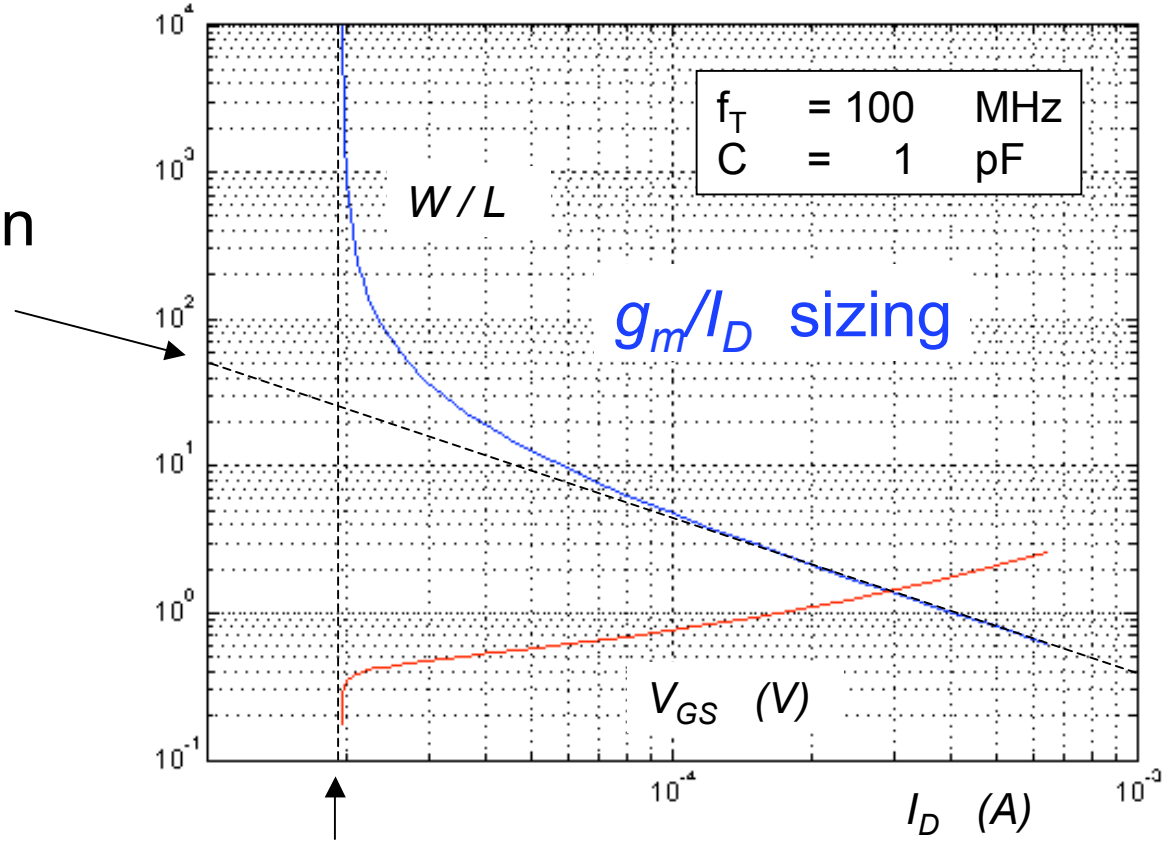
```
% data
fT    = 1e8;
C     = 1e-12;        } specs
n     = 1.2;
Isu   = 1e-6;
VTo   = 0.4;

% compute
UT    = .026;
ωT    = 2*pi*fT;
gm    = ωT*C;
qF    = logspace(-4,1.5,50);
gmoverID = 1./(n*UT*(1+qF));
ID    = gm./gmoverID;
IDu   = Isu*(qF.^2 + qF);
WsL   = ID./IDu;
VP    = UT*(2*(qF+1) + log(qF));
VG    = n*VP + VTo;

% plot
loglog(ID,WsL,'b',ID,VG,'r');
```

sizing the Intrinsic Gain Stage by means of the E.K.V. model

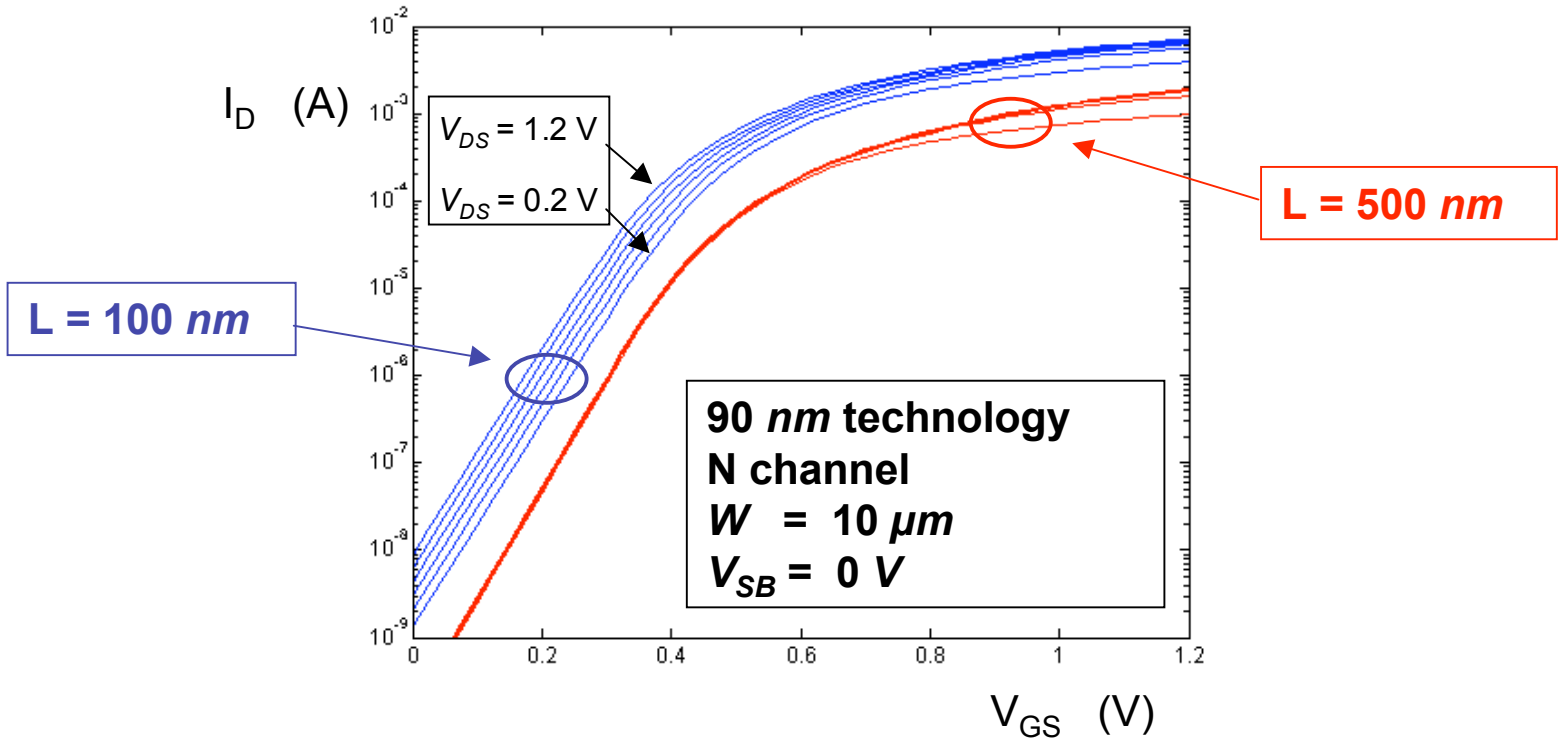
strong inversion approx.



weak inversion approx.

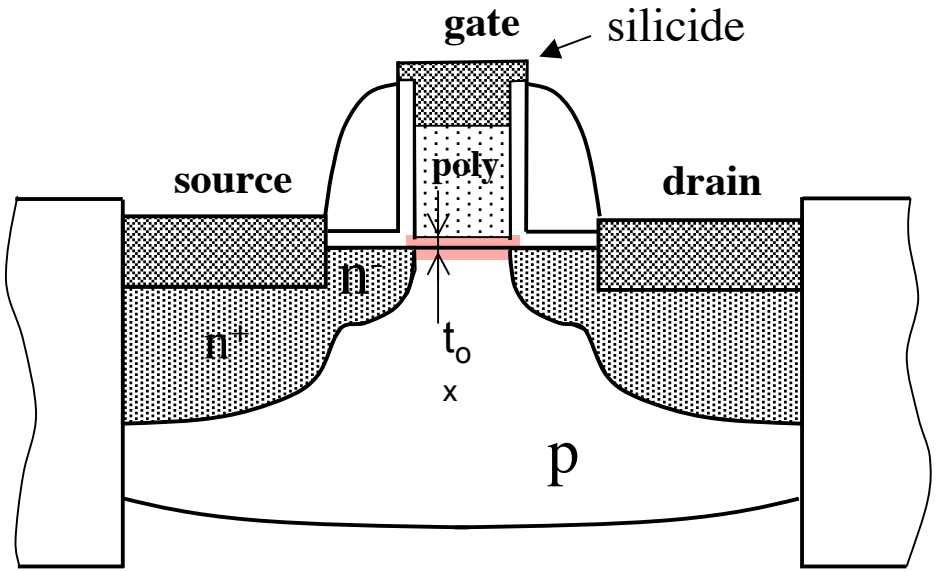
- The basic EKV / ACM model does not apply to short channel devices!

- Real $I_D(V_{GS})$ characteristics however look very similar.



- The spatial distribution of electrical fields in the substrate boils down to a 2D problem controlled mainly by L, V_{SB}, V_{DS}, little by V_{GS}.
- The inversion layer confines to a 1D problem controlled by V_{GS} and L, V_{SB}, V_{DS}.

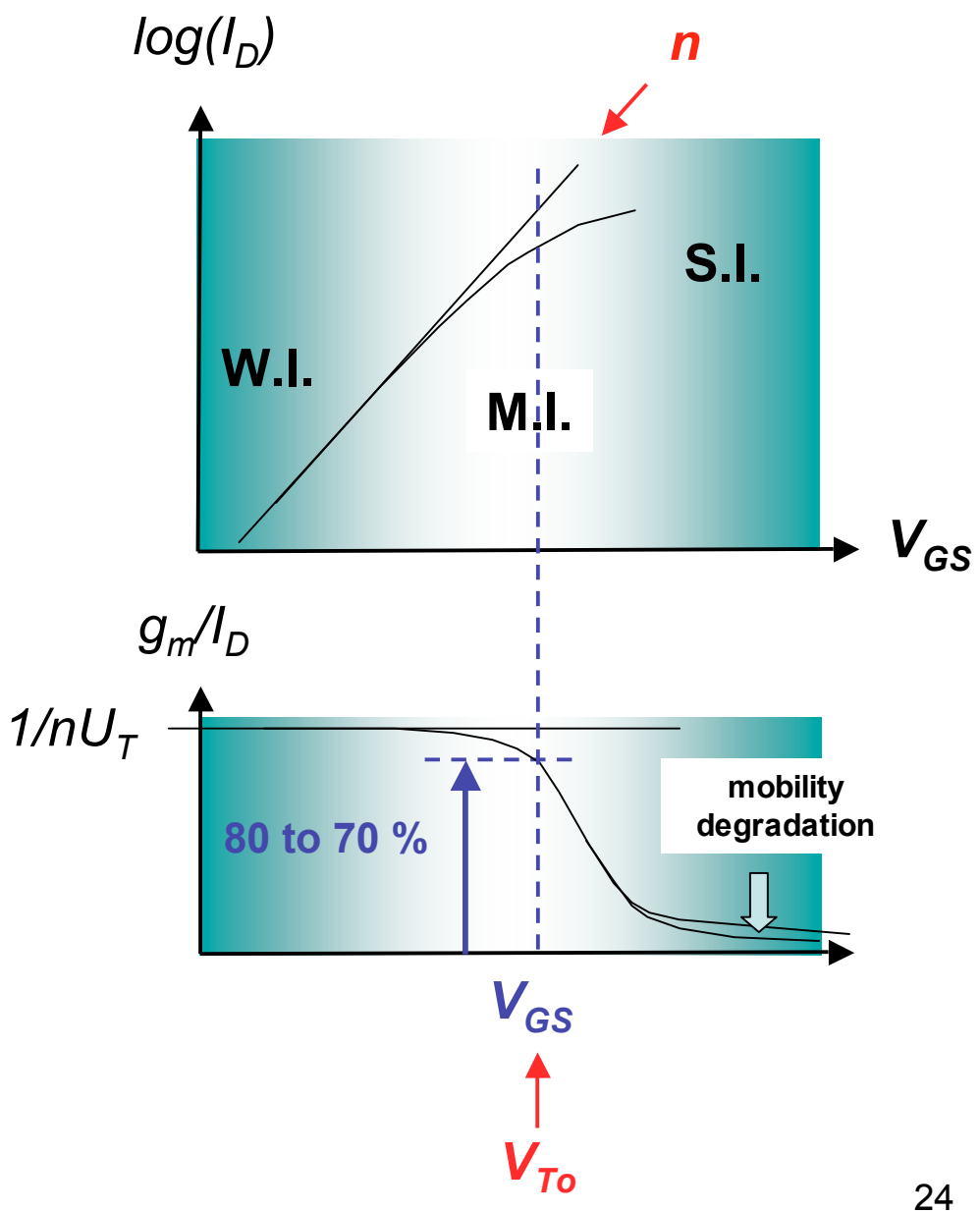
- Is it possible to model $I_D(V_G)$ characteristics by means of the EKV / ACM model with parameters that are functions of L, V_S and V_D.?



E.K.V. Identification

to be performed in the common source configuration

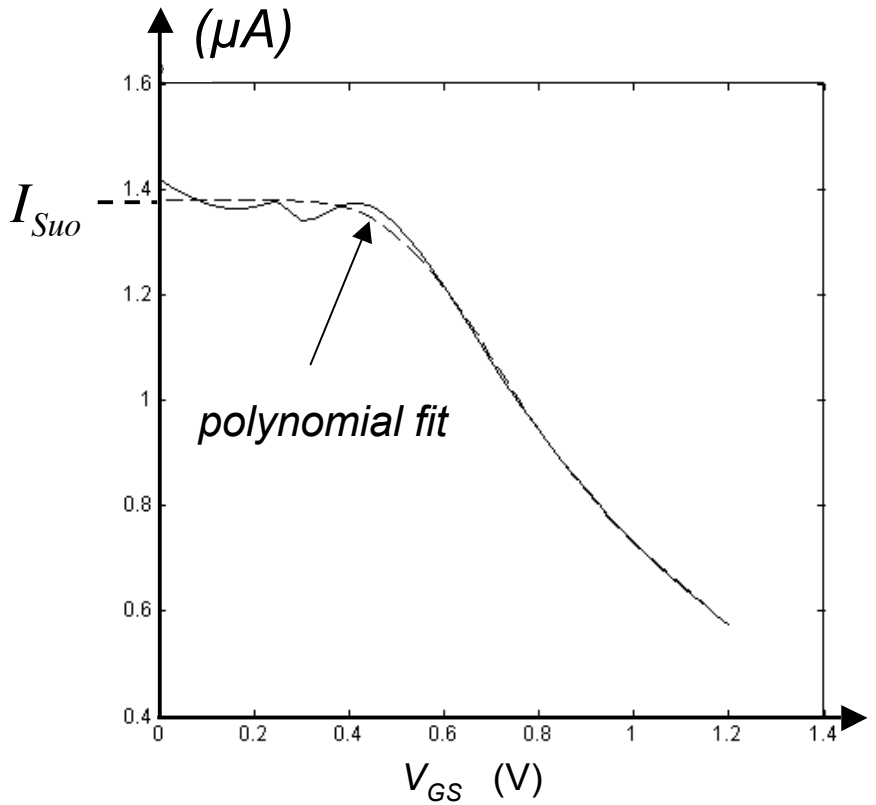
For L, V_S and V_{DS}



I_{su} (specific current)

$$\frac{I_{Du}(V_{GS})}{i} = I_{Su}(V_{GS})$$

$$\frac{V_{GS} - V_{To}}{n} = V_P \rightarrow q$$

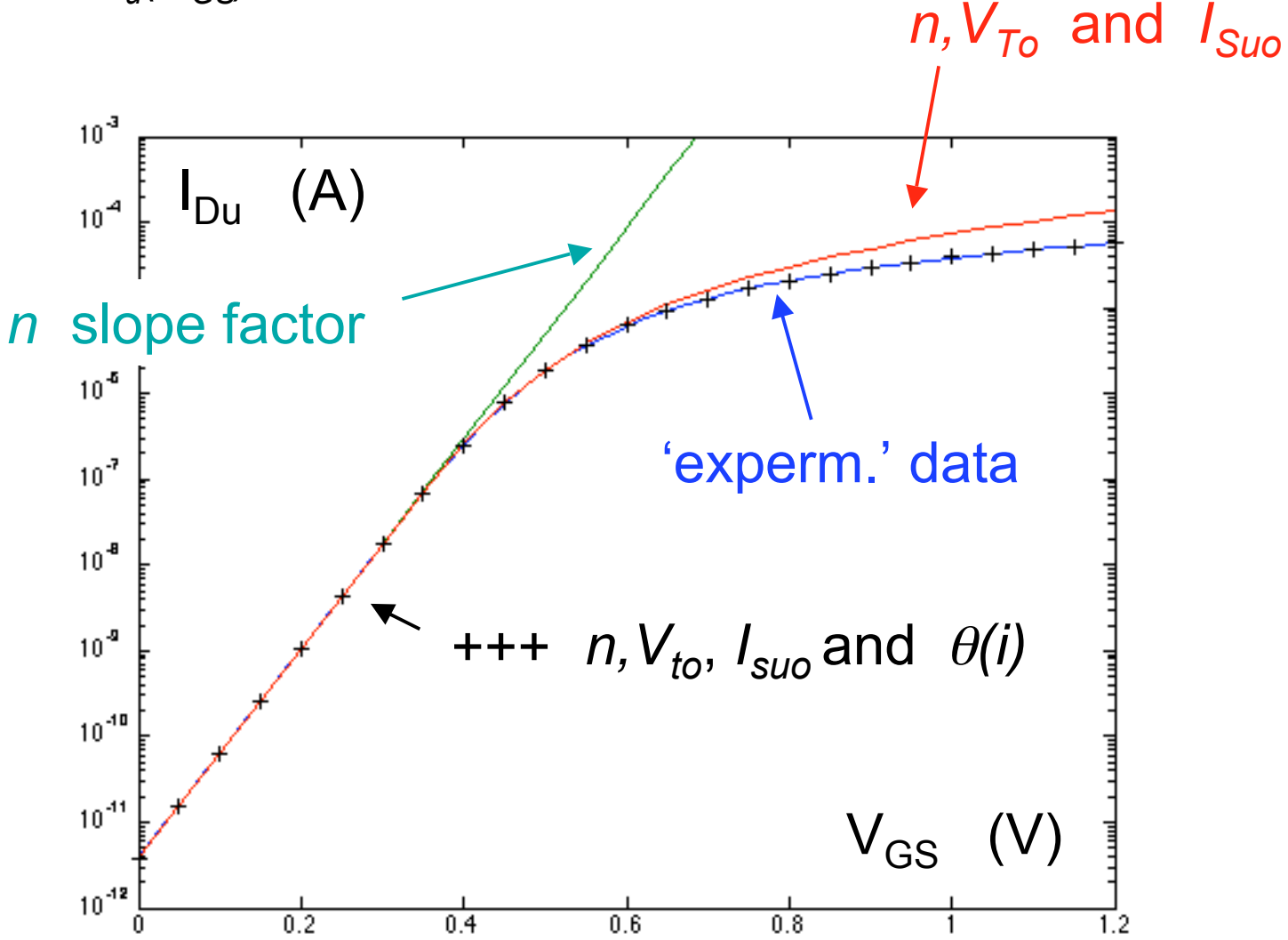


$$I_{Su} = \underbrace{2nU_T^2 \mu_o C'_{ox}}_{I_{Suo}} \theta(i)$$

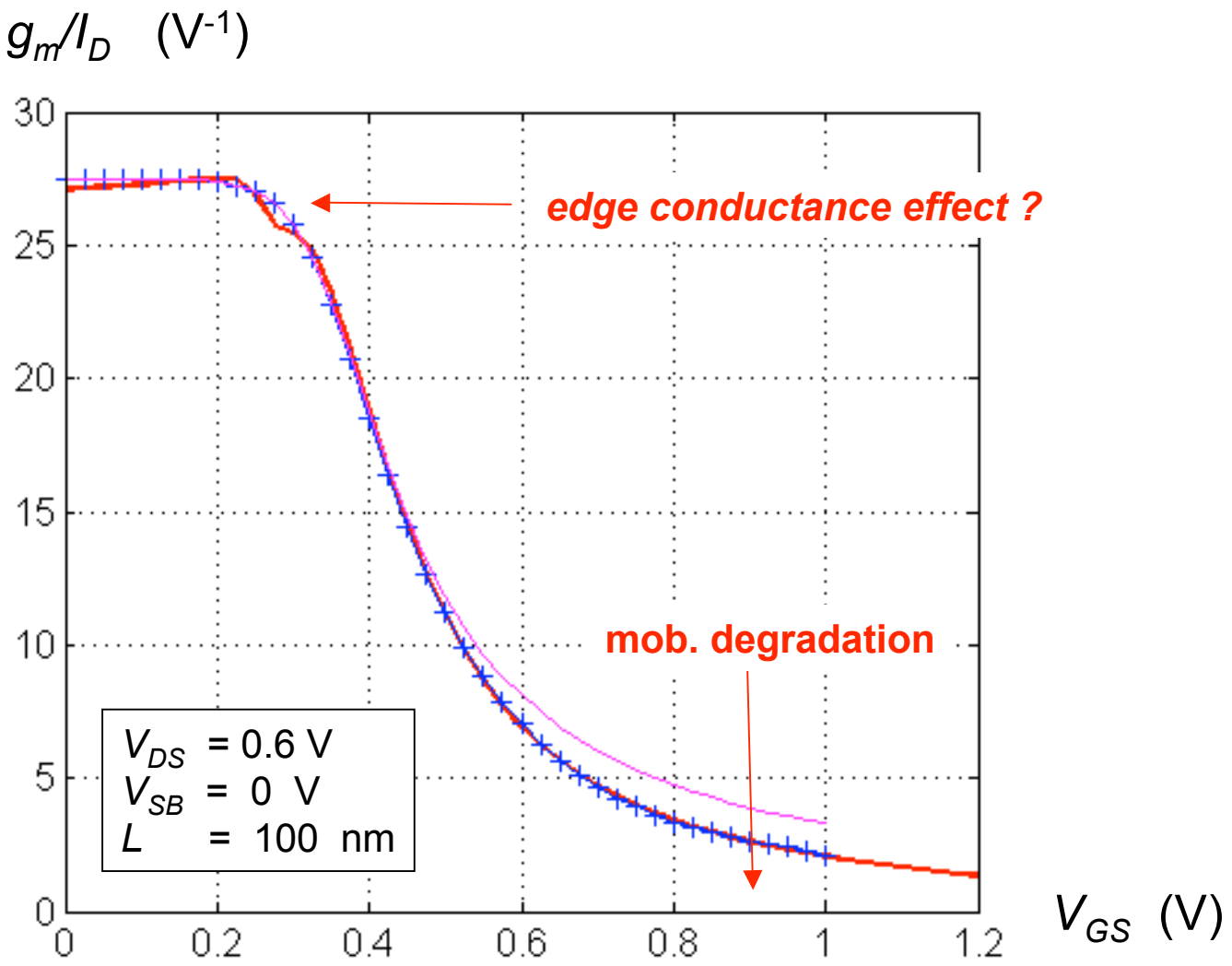
mobility degradation factor

For L, V_S and V_{DS}

Verification : $I_u(V_{GS})$ *reconstruction*



N-channel; L = 100 nm; V_{DS} = 0.6 V; V_{SB} = 0.6 V.


g_m/I_D (V^{-1})
30
25
20
15
10
5
0
0
0.2
0.4
0.6
0.8
1
1.2
edge conductance effect ?
mob. degradation
V_{DS} = 0.6 V
V_{SB} = 0 V
L = 100 nm
V_{GS} (V)
'experimental'
model
model (no mob degradation)

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Conclusion

$\frac{g_m}{I_D}$ does not depend on W

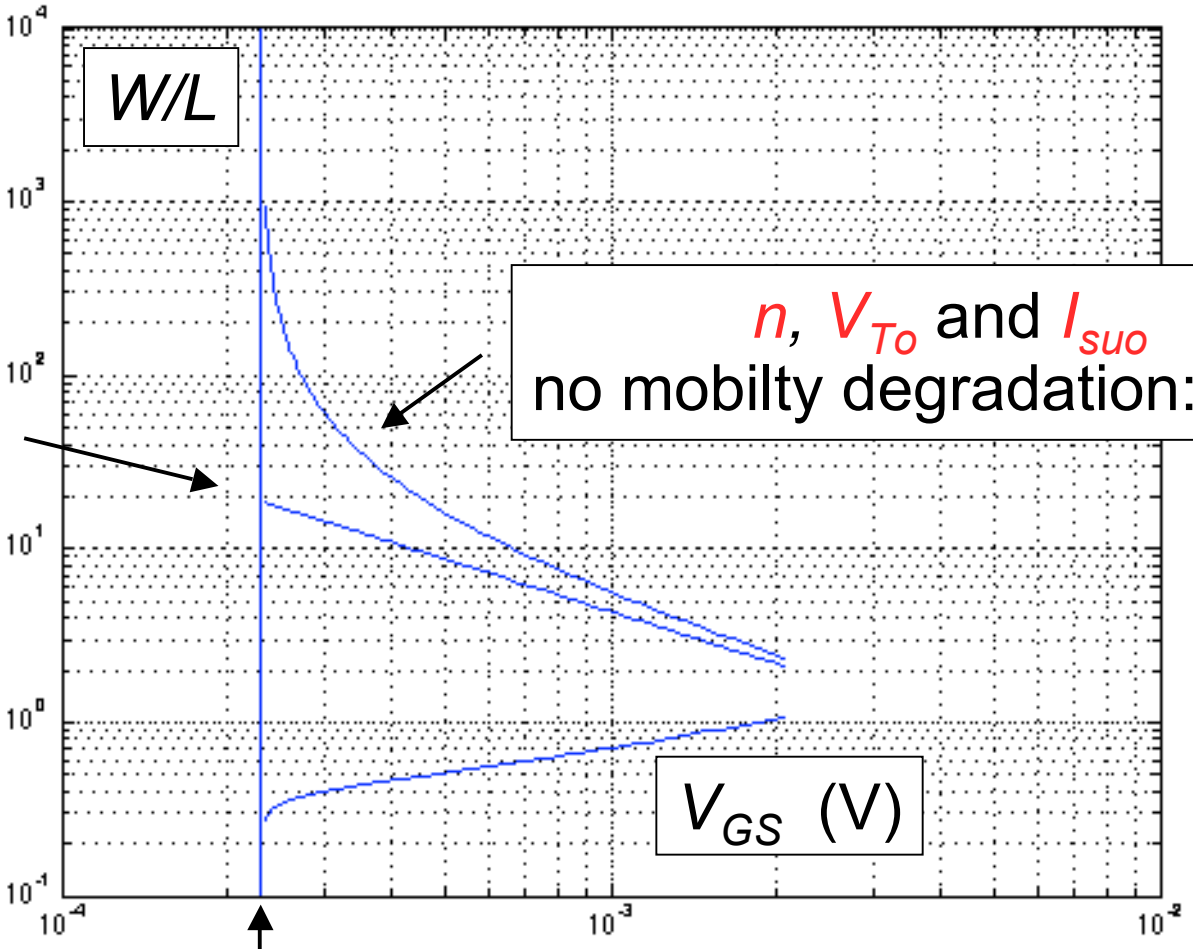
as long as $W >> W_{min}$

(true for most analogue circuits)

depends on L, V_{DS} and V_{SB} for

- V_T roll-off
- D.I.B.L.
- C.L.M.
- mobility degradation
- ….

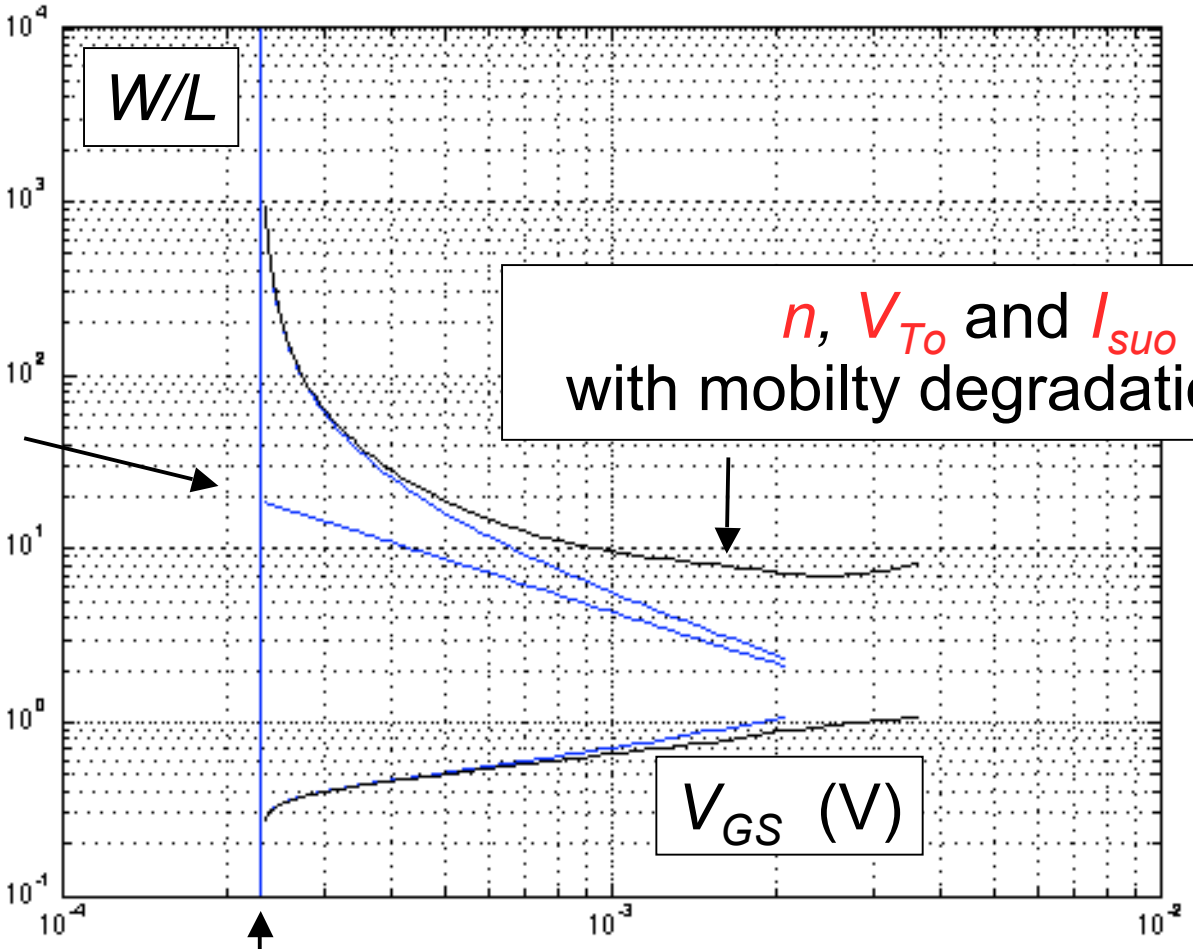
f_T = 1 GHz; C_o = 1 pf; L = 120 nm; V_S = 0; V_{DS} = 0.6 V;



strong inversion approx.

weak inversion approx.

f_T = 1 GHz; C_o = 1 pf; L = 120 nm; V_S = 0; V_{DS} = 0.6 V;



strong inversion approx.

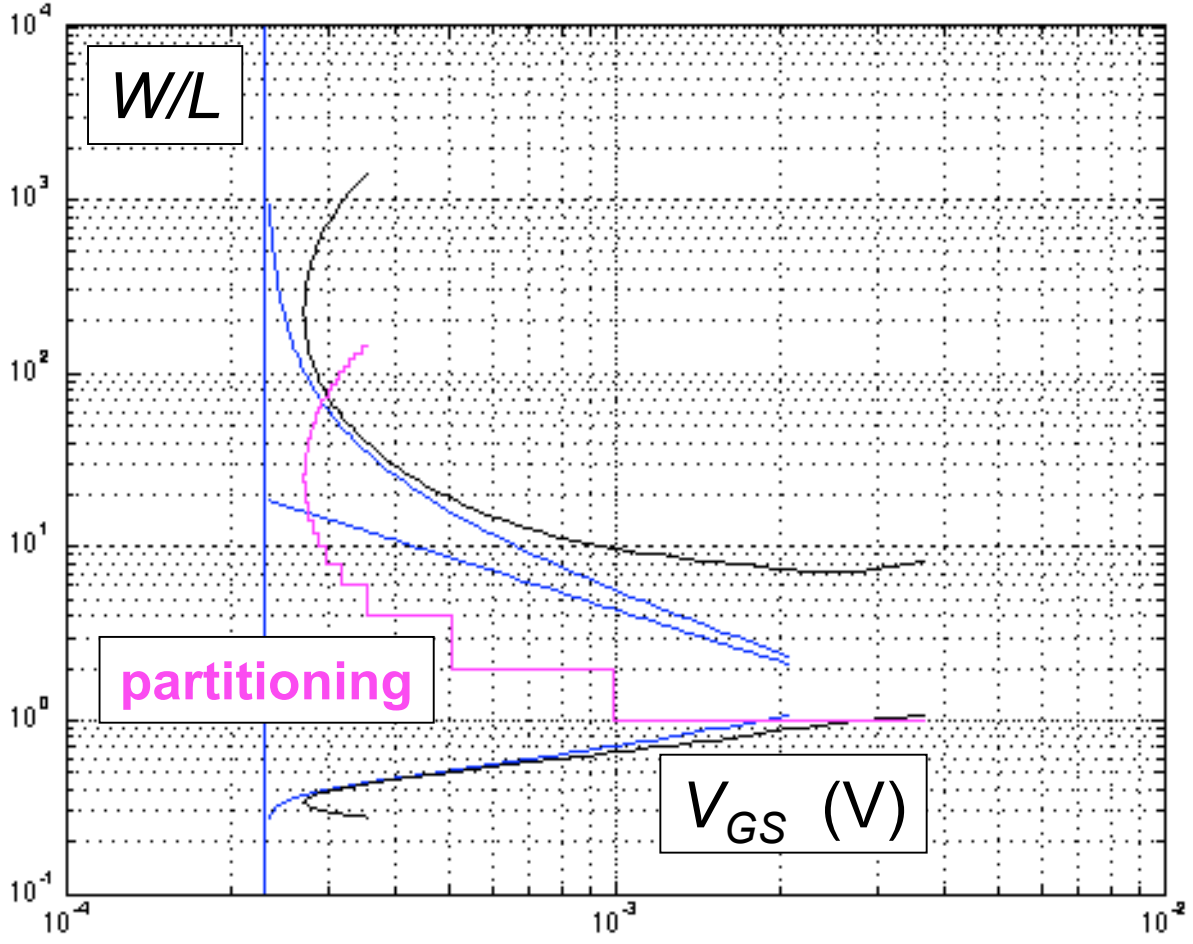
n, V_{To} and I_{suo} with mobilty degradation: $\theta(\iota)$

I_D (A)

weak inversion approx.

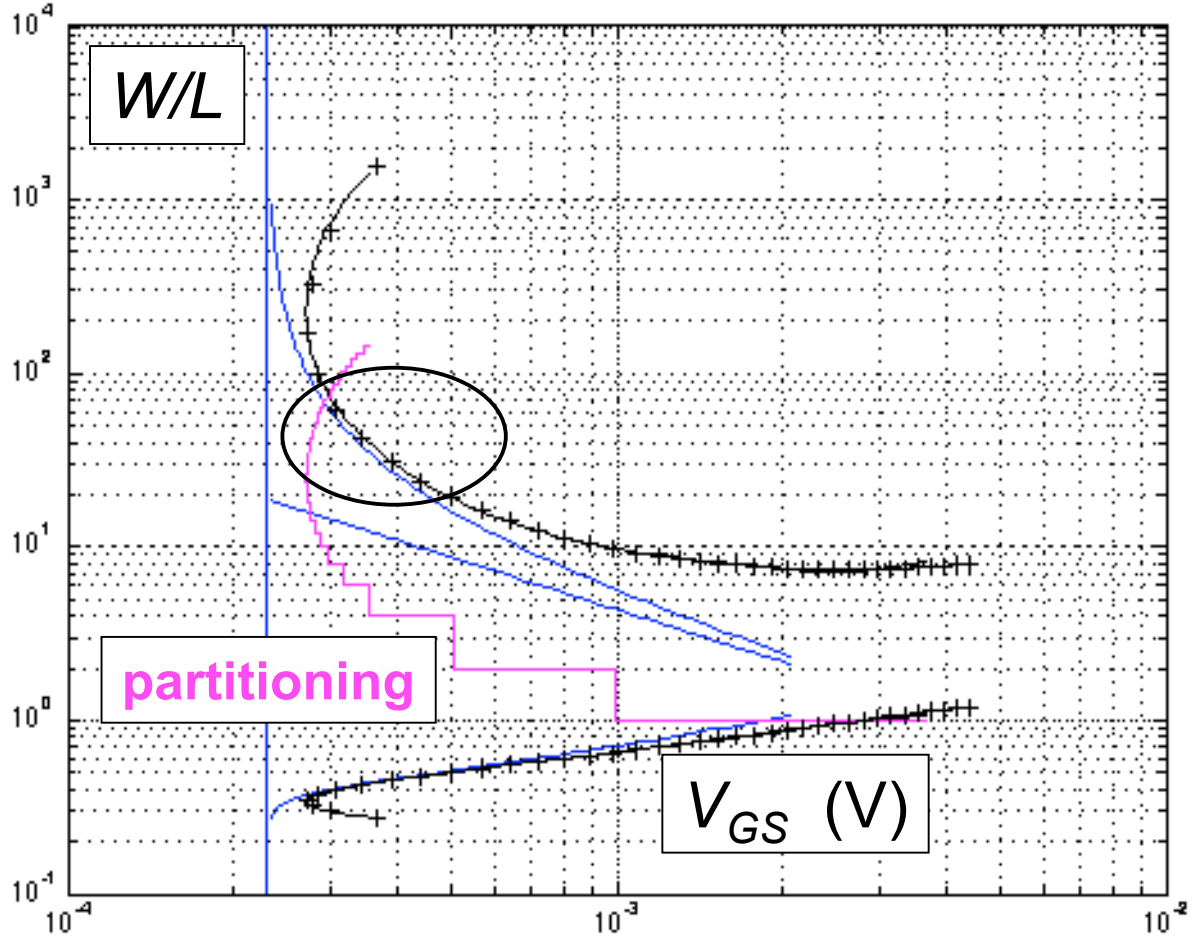
Add drain junction cap. to C_o

f_T = 1 GHz; C_o = 1 pf; L = 120 nm; V_S = 0; V_{DS} = 0.6 V; Wmax = 1 µm;



Comparison with semi-empirical method (+++)

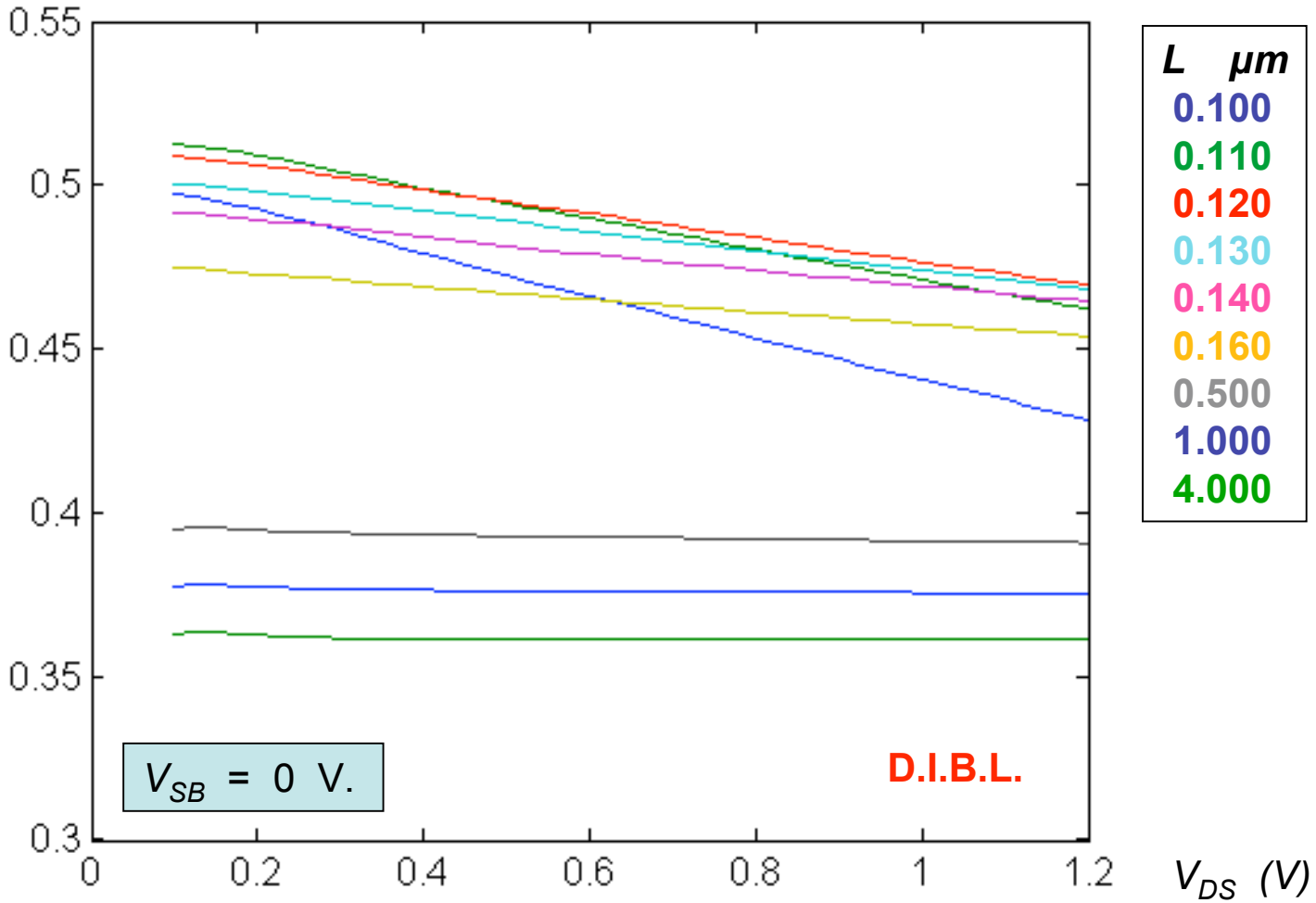
f_T = 1 GHz; C_o = 1 pf; L = 120 nm; V_S = 0; V_{DS} = 0.6 V; Wmax = 1 µm;



Param. dependence on V_{DS}

1) n small

2) V_{To} ⟶

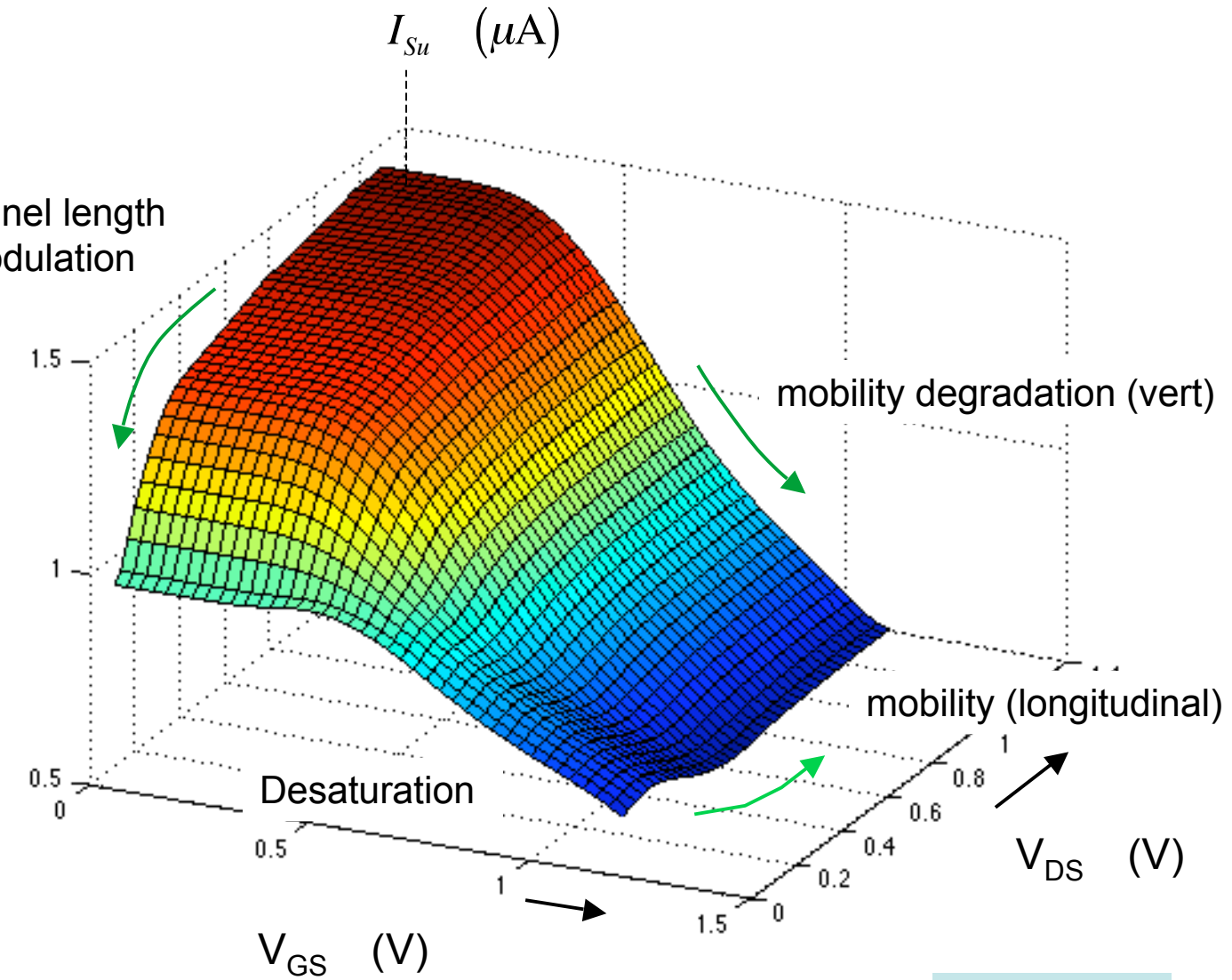


Param. dependence on V_{DS}

1) n small

2) V_{To}

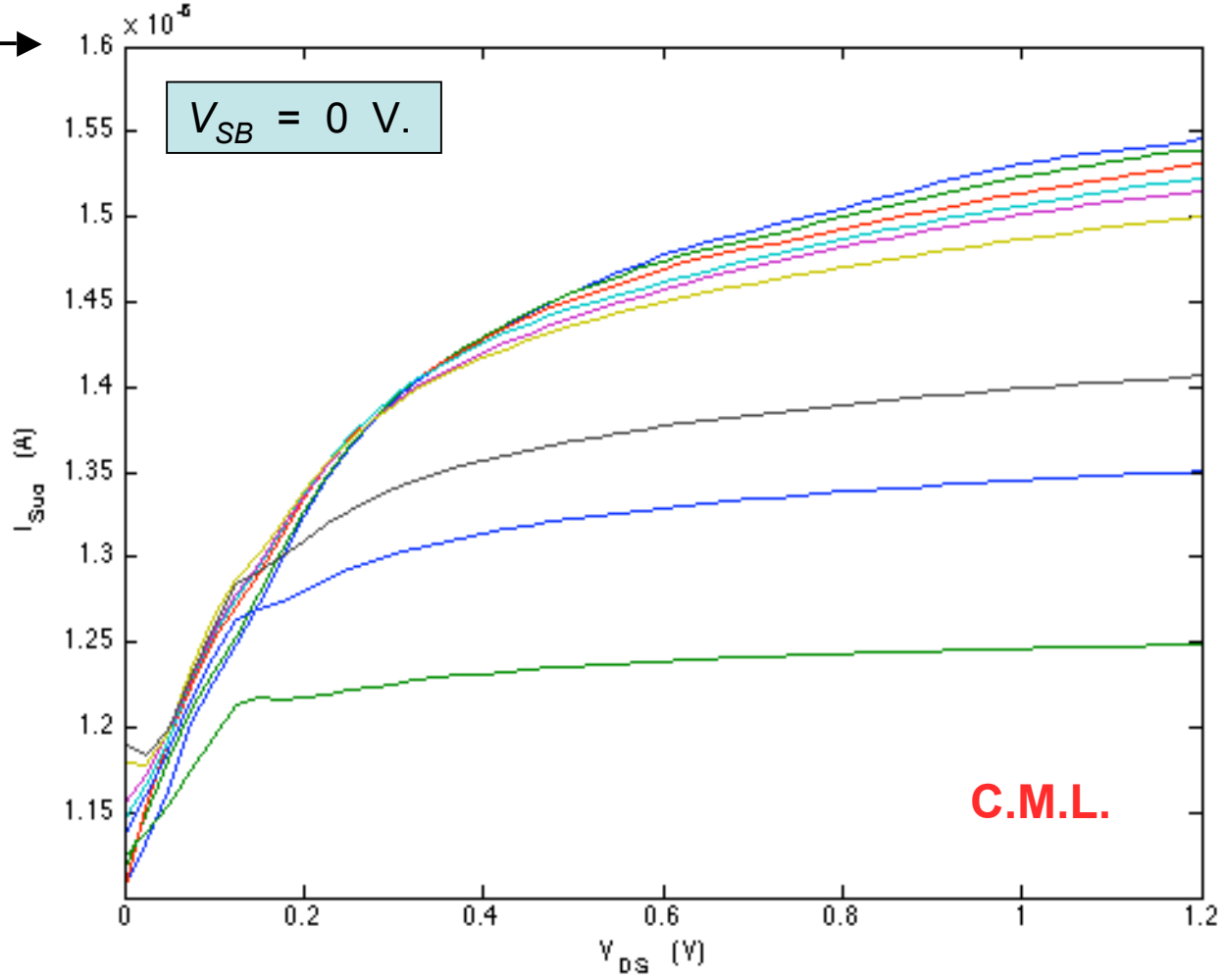
3) I_{Su}



V_{SB} = 0 V.

Param. dependence on V_{DS}

1) *n* small
2) V_{To}
3) I_{Suo} →



L μm
0.100
0.110
0.120
0.130
0.140
0.160
0.500
1.000
4.000

Param. dependence on V_{DS}

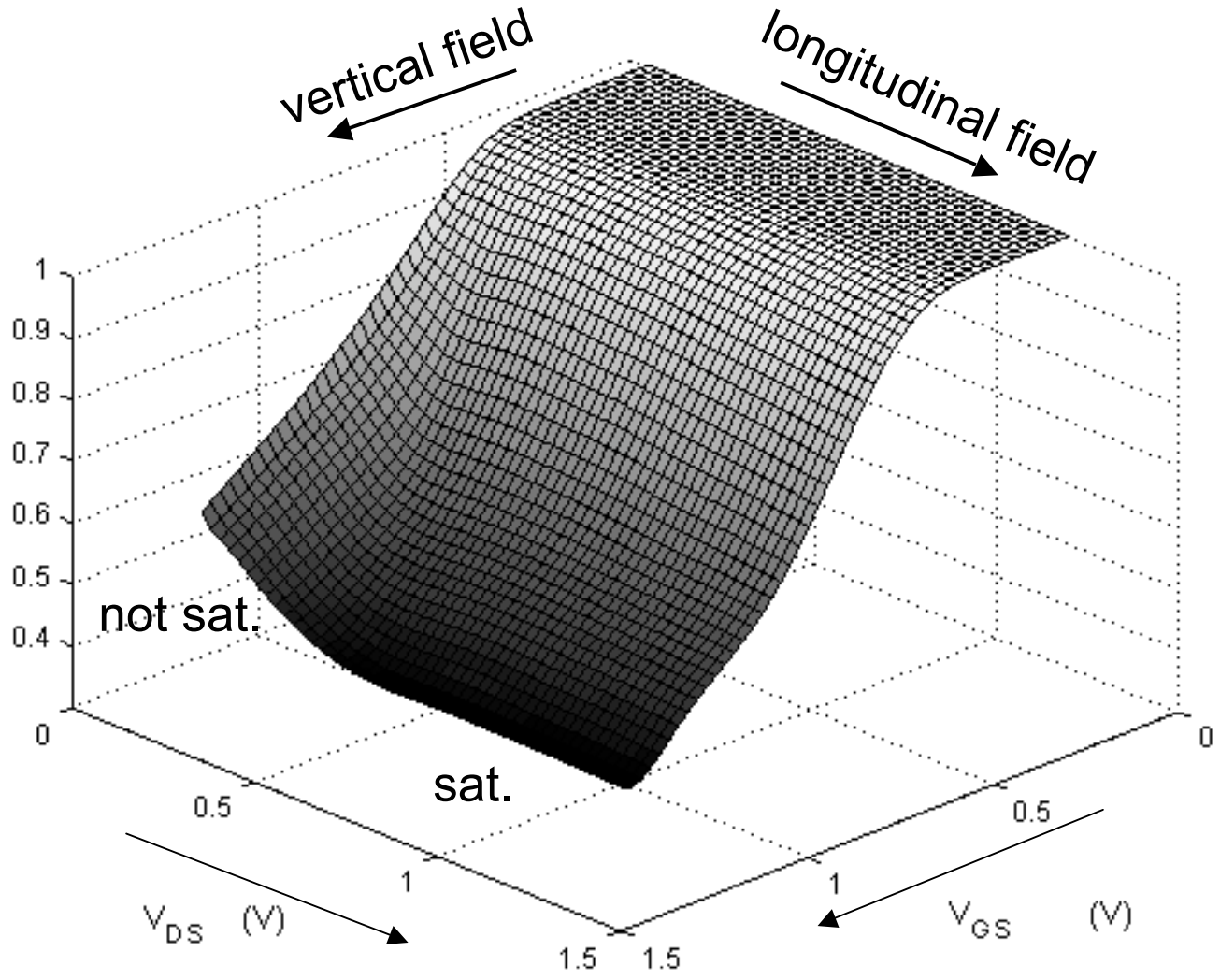
1) n small

2) V_{To}

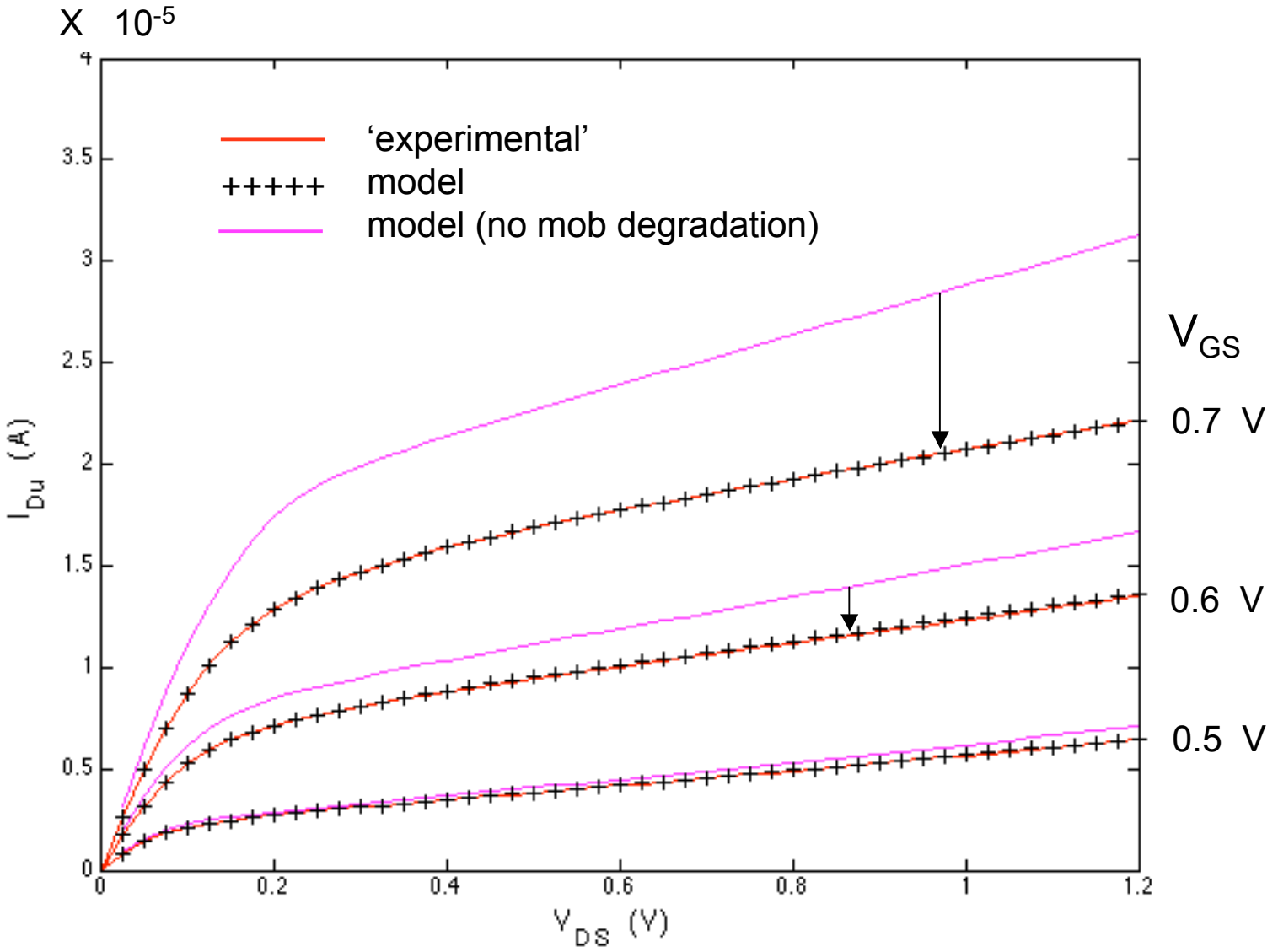
3) I_{suo}

4) $\theta(i)$ →

V_{SB} = 0 V.



Verification : $I_{Du}(V_{DS})$ reconstruction (S.I.)



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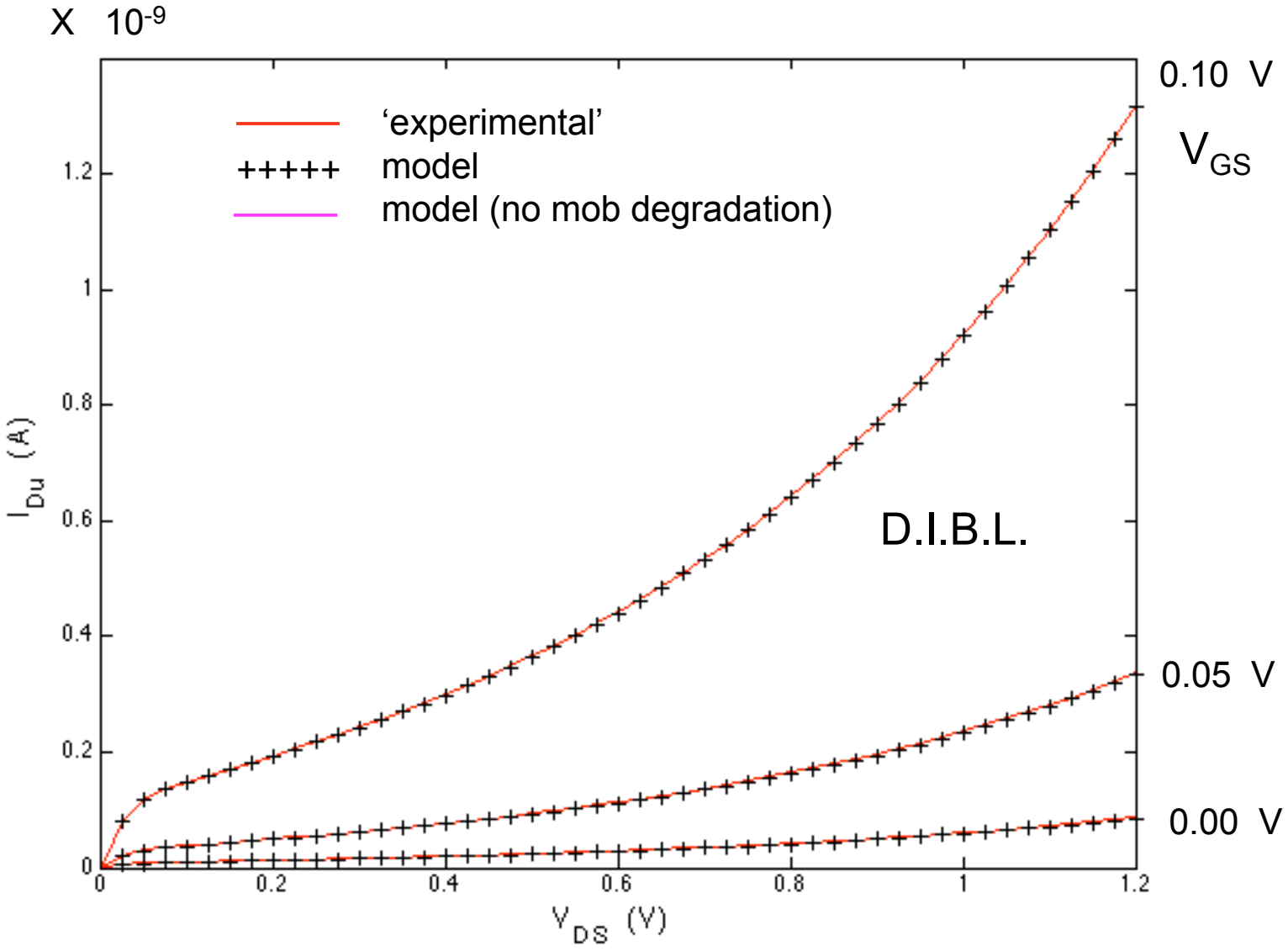

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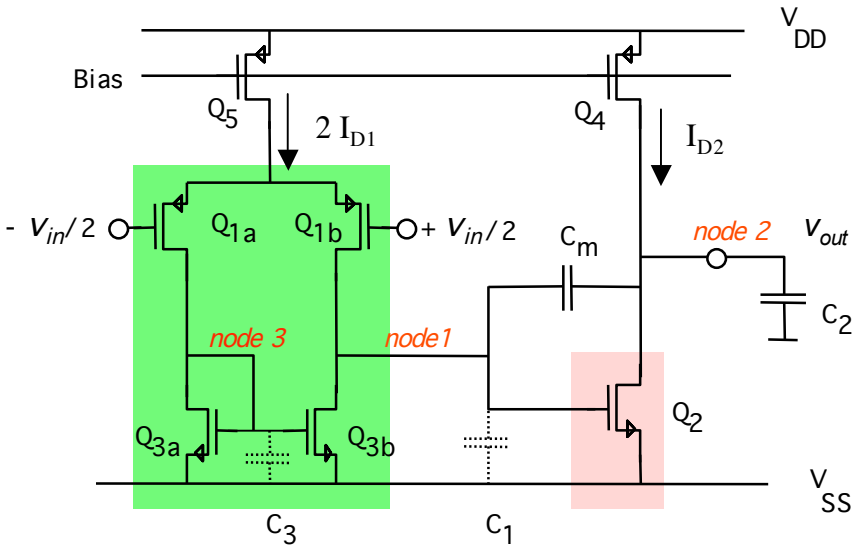
- the Miller Op. Amp.

Conclusion

1) fix NDPole and Zero with respect to ω_T to meet phase margin



$$\omega_T = \frac{g_{m1}}{C_m}$$

$$z = \frac{g_{m2}}{C_m} = Z\omega_T$$

$$\omega_{ndp} = \frac{g_{m2}}{C_m}\frac{C_m^2}{(C_1+C_2)C_m + C_1C_2} = NDP\,\omega_T$$

e.g. Z = 10 and NDP = 4… 5
for phase margin of approx. 60°

2) Size the 'A' transistors.

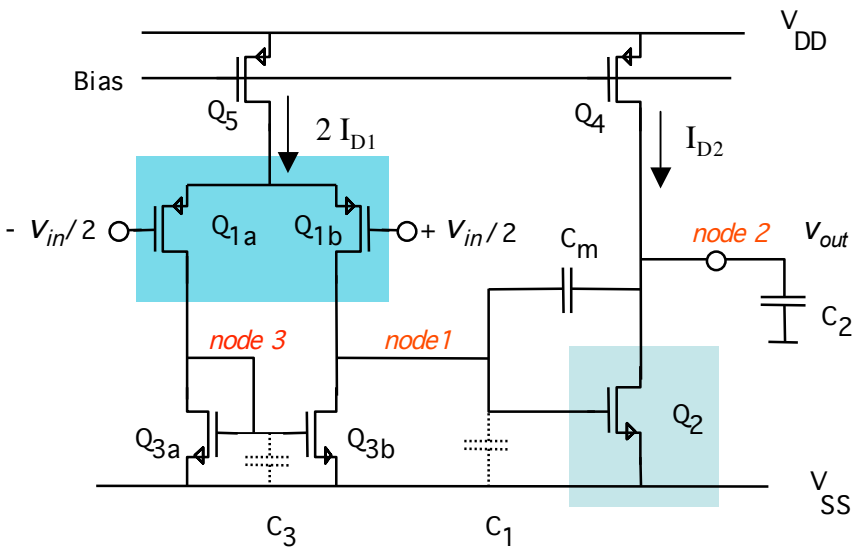
spec. initial guess

$$g_{m1} = \omega_T C_m$$

$$I_{D1} = \frac{g_{m1}}{\left(\frac{g_m}{I_D}\right)_1}$$

$$\frac{W_1}{L_1} = \frac{I_{D1}}{I_{Du1}}$$

q_{F1}



$$g_{m2} = Z\, g_{m1}$$

$$I_{D2} = \frac{g_{m2}}{\left(\frac{g_m}{I_D}\right)_2}$$

$$\frac{W_2}{L_2} = \frac{I_{D2}}{I_{Du2}}$$

q_{F2}

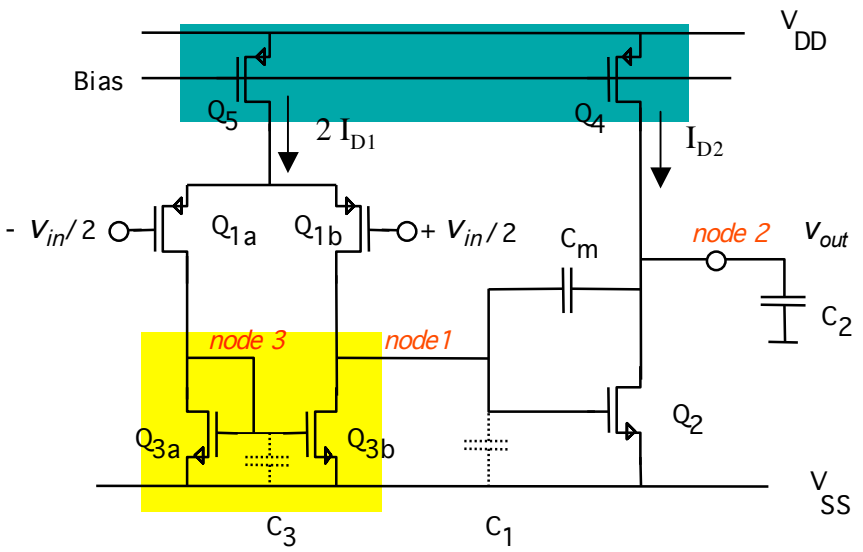
3) Size the 'B' transistors.

more constraints

- zero systematic offset

$$V_{G3} = V_{G2}$$

$$\left(\frac{W}{L}\right)_3 = \frac{I_{D1}}{I_{Du2}}$$



- choose bias so that Q4 and Q5 are in strong inversion

$$I_{Du4} = I_{Du5}$$

$$\left(\frac{W}{L}\right)_4 = \frac{I_{D2}}{I_{Du4}}$$

$$\left(\frac{W}{L}\right)_5 = \frac{2I_{D1}}{I_{Du4}}$$

4) Estimate C_1, C_2, C_3 and compute C_m

Choose …

L_1 medium (voltage gain)
L_2 min. size
L_3 large for min 1/f noise (beware from doublet!)
L_4 matching + size
L_5 matching + common mode rejection

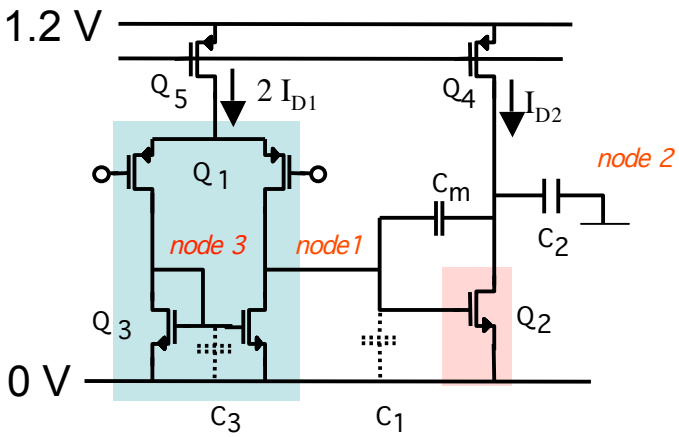
- the parasitic cap. are estimated knowing W's and L's + techno. data
- a new C_m is extracted from inverted NDP equation

$$C_m = 0.5\frac{NDP}{Z}\cdot\left[C_1 + C_2 + \sqrt{(C_1 + C_2) + 4\frac{Z}{NDP}C_1 C_2}\right]$$

reiterate until C_m gets constant

example

Spec: f_T = 50 MHz;
C = 1 pF;
VDD = 1.2 V;



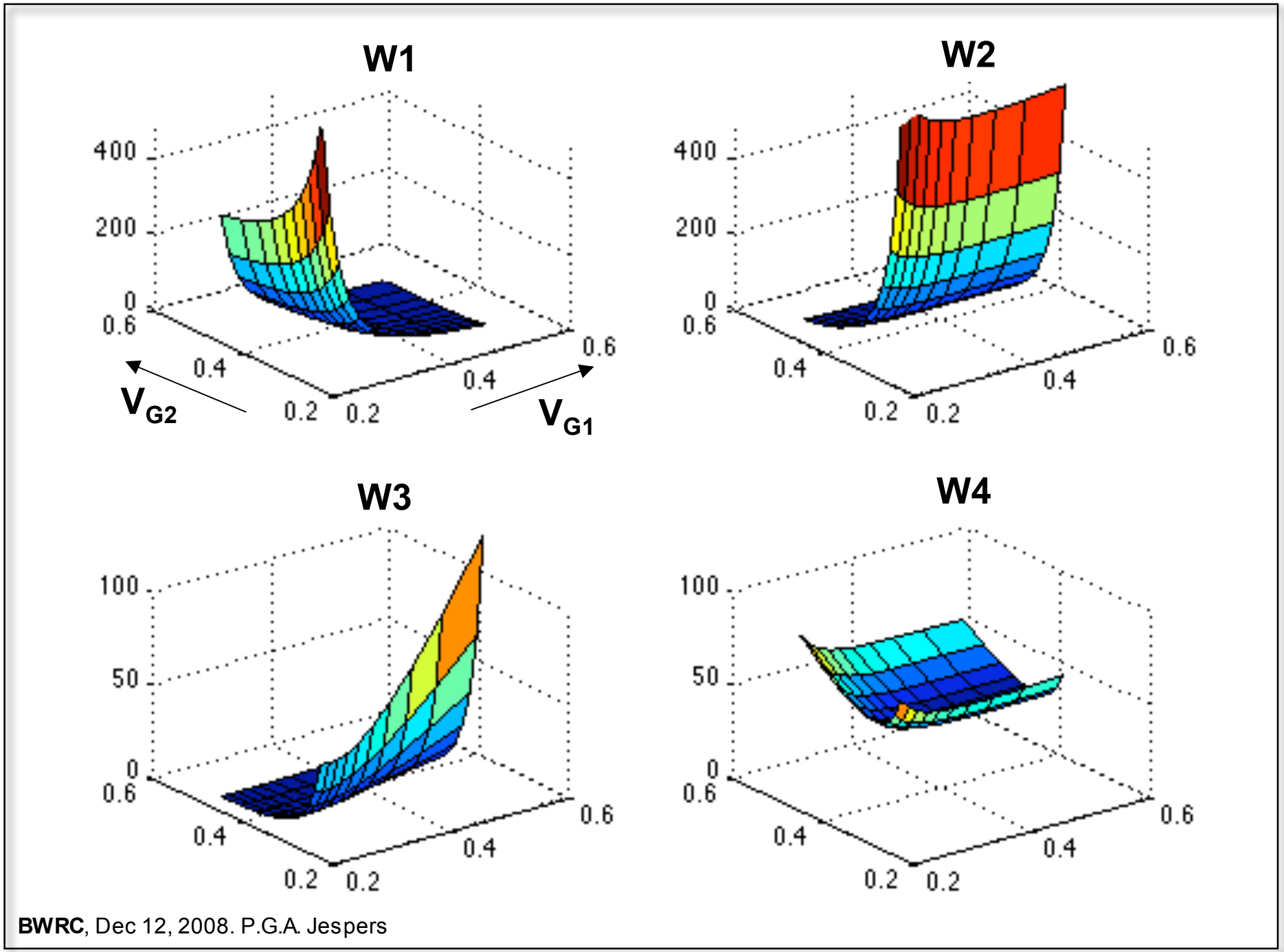
q_{F1} = 0.0316 --> 3.16
q_{F2} = 0.10 --> 2
q_{F4} = 2,90

q_F exploration space

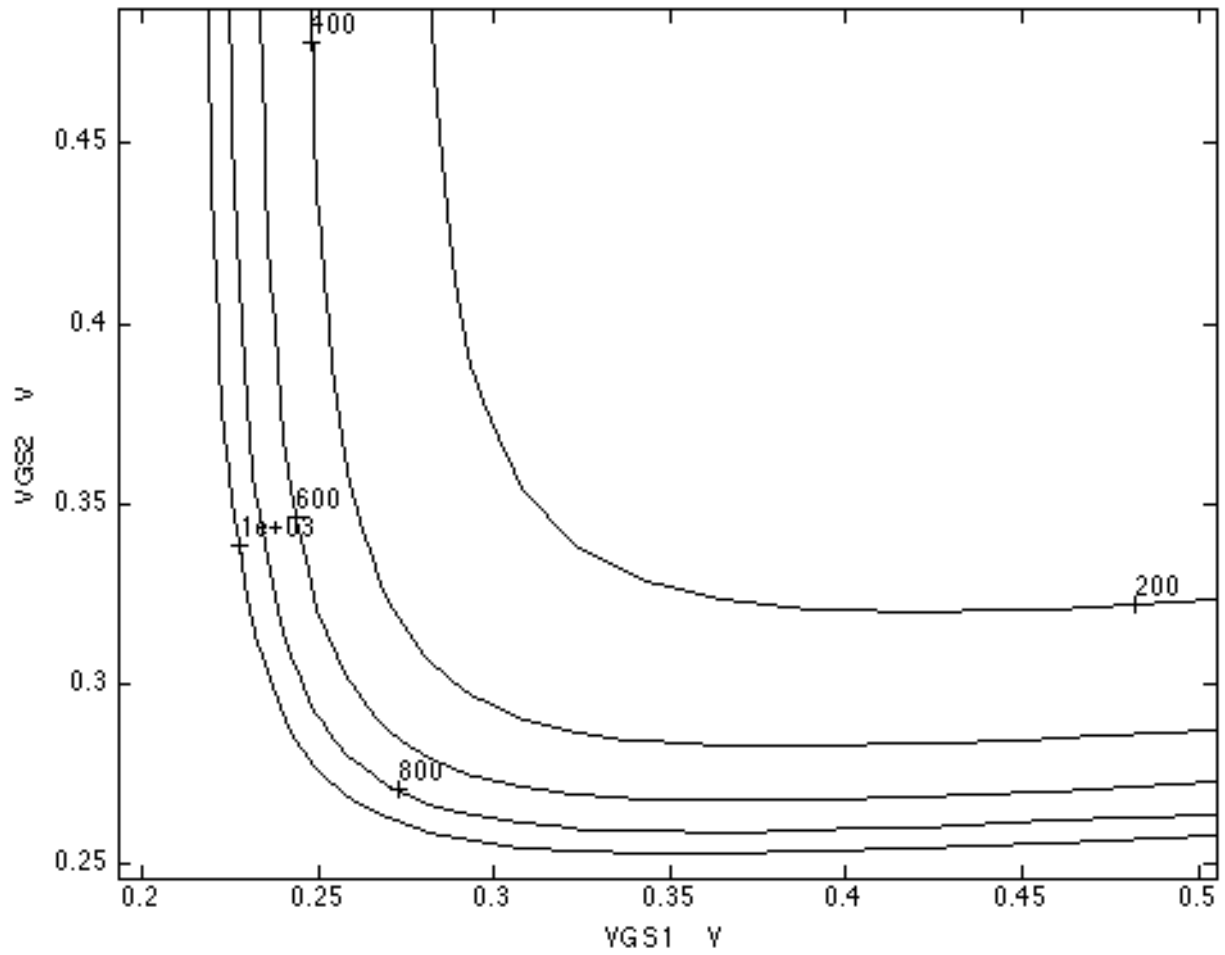
Z = 10
NDP = 4

phase margin

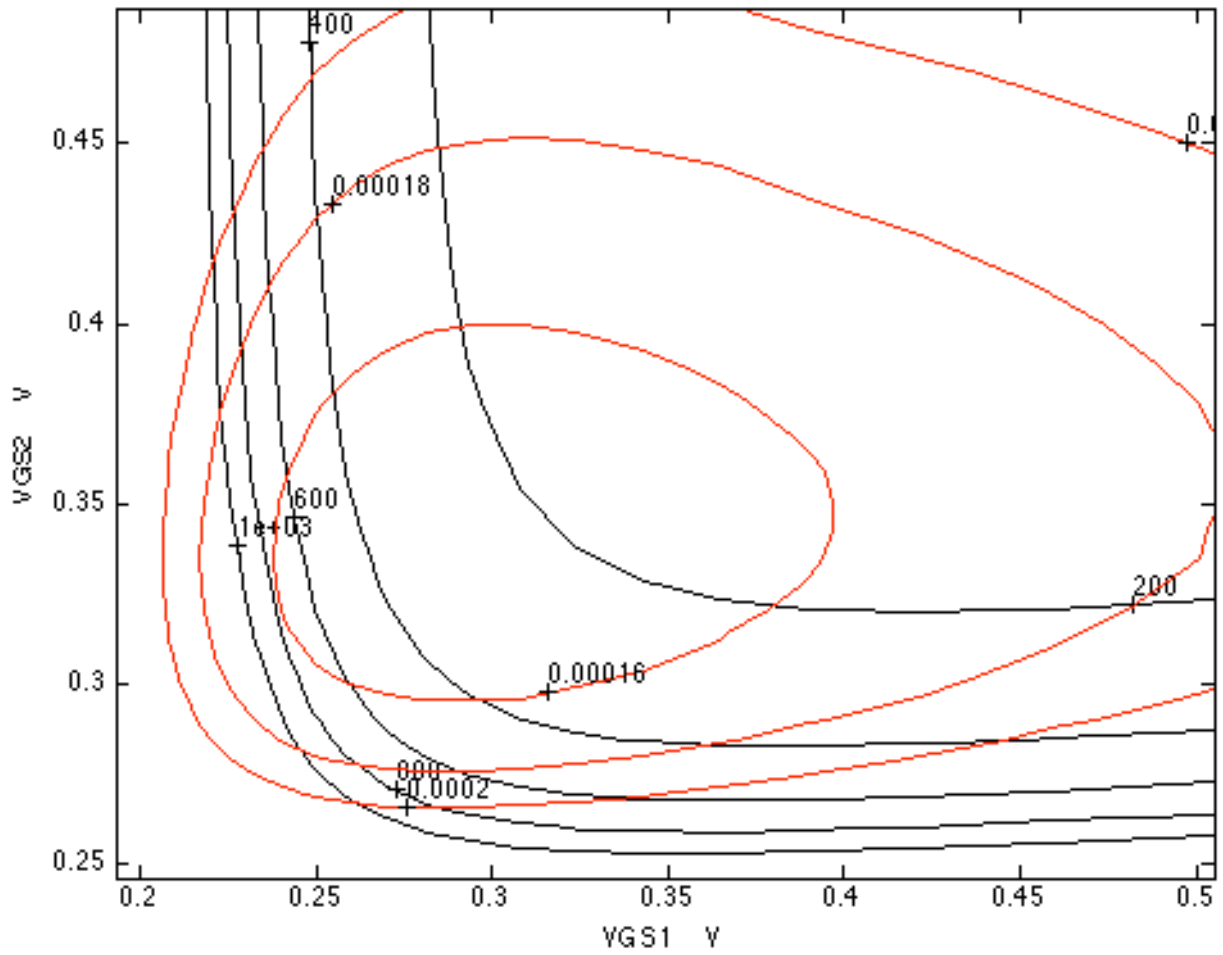
L1 = 1 µm
L2 = 0.5 µm
L3 = 1 µm
L4 = 0.5 µm
L5 = 1 µm



BWRC, Dec 12, 2008. P.G.A. Jespers

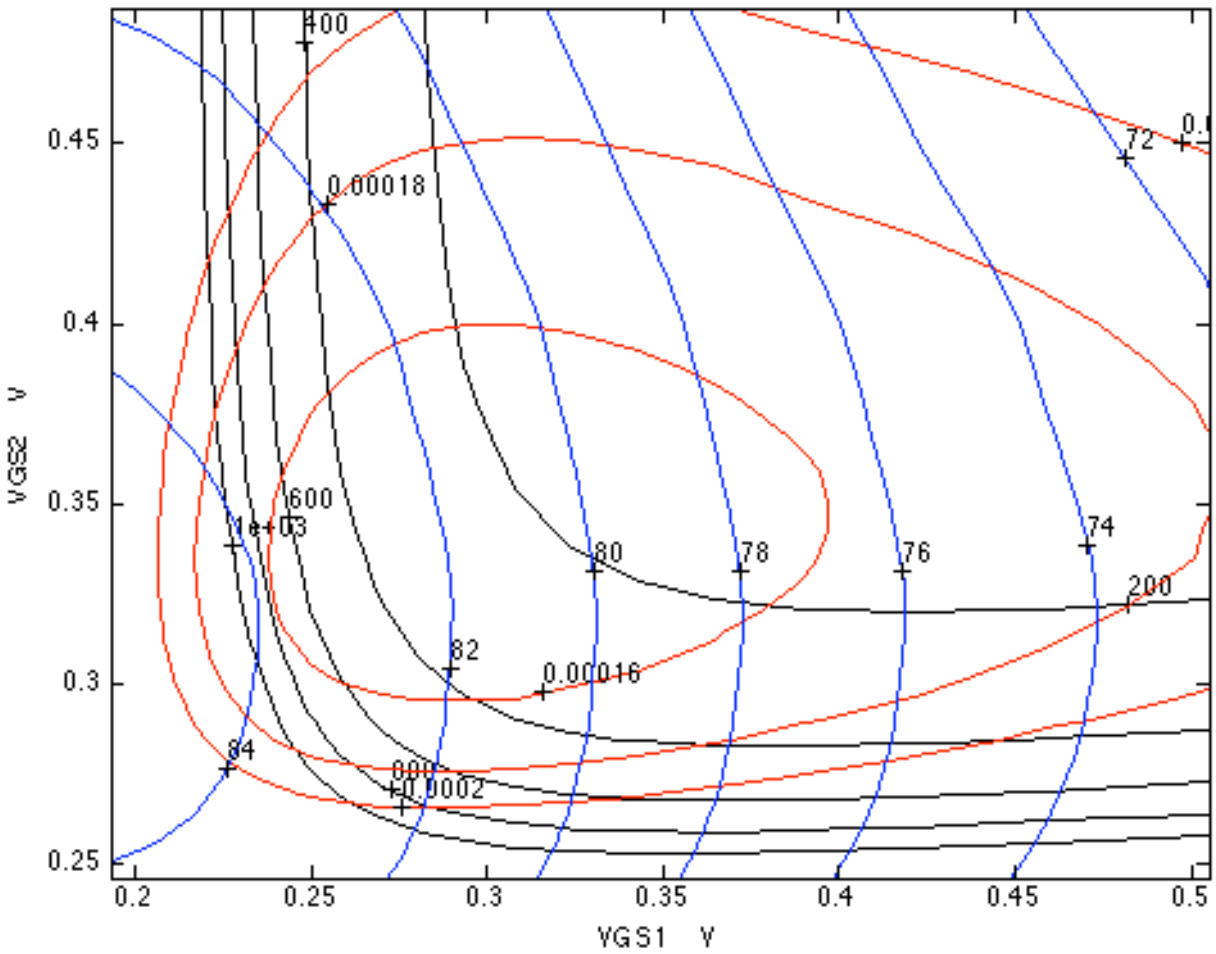


constant active area (μm^2)

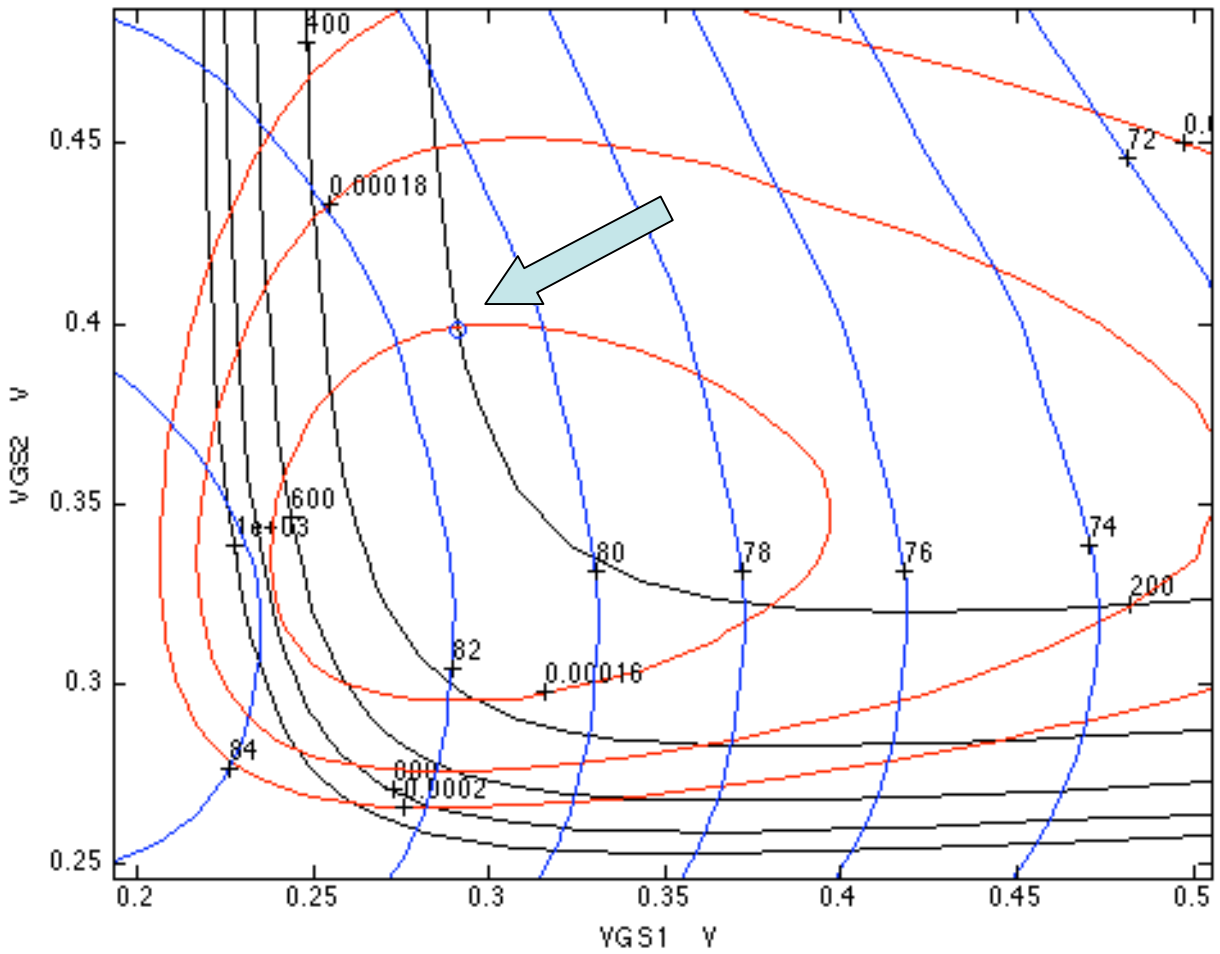


constant supply (A)

constant active area (μm^2)



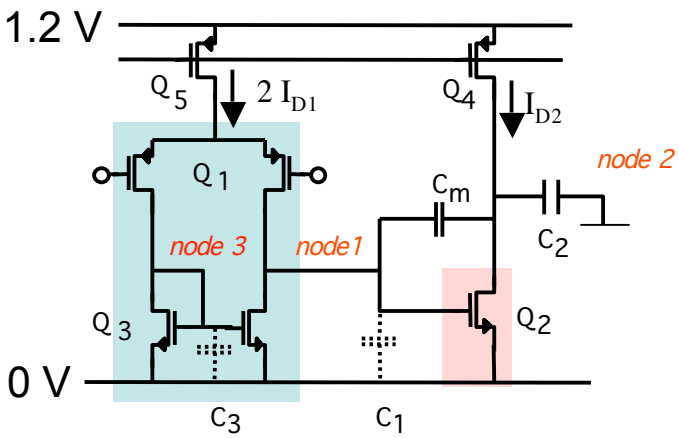
constant gain (dB)
constant supply (A)
constant active area (μm^2)



constant gain (dB)
constant supply (A)
constant active area (μm^2)

The selected point

	Q1	Q2	Q3	Q4	Q5
qF	0.433	1.065	1.236	2.90	2.90
VGS (V)	0.29	0.40	0.40	0.49	0.49
I (µA)	2 x 8.1	143.7	2 x 8.1		
W / L (µm)	67.3 / 1	47.5 / 0.5	2.23 / 1	57.83 / 0.5	7.69 / 1
gain (dB)	45.1	39.2			
	0.1965 C1 pF	1.0375 C2 pF	0.0576 C3 pF	0.6242 Cm pF	



gain = 81 dB
power consump. = 191 µW

Conclusion

g_m/I_D

- relates a small signal param. to a large signal quantity
- does not vary with transistor widths
- controls the mode of operation, power consump, gain ...

paves the way for sizing CMOS circuits

- semi-empirically
  (look-up tables : I_D, g_m, g_d, ..)
- by means of the E.K.V./A.C.M. model
  (parameters look-up tables or fitting functions)
  - simple expressions of I_D, g_m/I_D, g_d/I_D
  - q_F monitors mode of operation
  - increased physical insight

suitable for sub-micron low-voltage low-power circuits

g_m/I_D sizing methodology for low-power/voltage CMOS circuits

by P.G A. Jespers

to be published 2009 by Springer

paul.jespers@uclouvain.be

A list of references concerning the g_m/I_D methodology:

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P. Jespers.
FTFC'2001 records, mai-juin, Paris, p.99-106

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