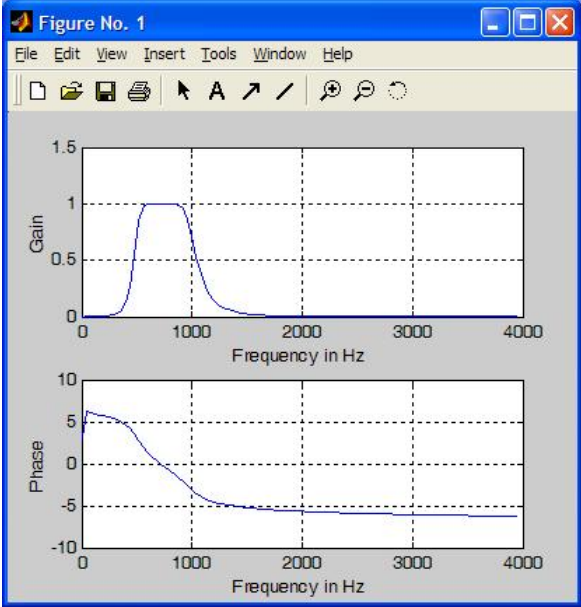
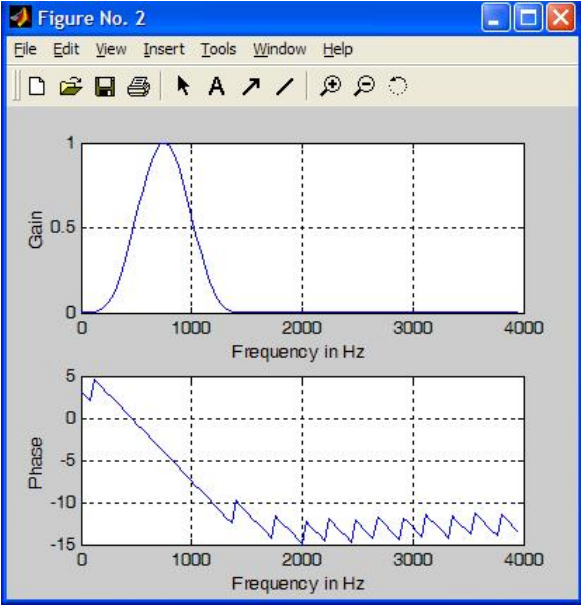


No.	Problem Examples
1	<p>Design IIR filter (Butterworth – 8th Orders), $f_{CL}=500\text{Hz}$, $f_{CH}=1000\text{Hz}$, $f_s=8000\text{Hz}$. Solution: To find a & b coefficients:- [b,a]= butter(4,[500 1000]/4000); zplane(b,a); help freqz [h,f]=freqz(b,a,100,8000); subplot(211),plot(f,abs(h));grid;xlabel('Frequency in Hz');ylabel('Gain') subplot(212),plot(f,unwrap(angle(h)));grid;xlabel('Frequency in Hz');ylabel('Phase');</p> 
2	<p>Design FIR filter (35th Orders), $f_{CL}=500\text{Hz}$, $f_{CH}=1000\text{Hz}$, $f_s=8000\text{Hz}$. To find b coefficients:- [b]= fir1(35,[500 1000]/4000); - by default in FIR a = 1 zplane(b,1); help freqz [h,f]=freqz(b,1,100,8000); subplot(211),plot(f,abs(h));grid;xlabel('Frequency in Hz');ylabel('Gain') subplot(212),plot(f,unwrap(angle(h)));grid;xlabel('Frequency in Hz');ylabel('Phase');</p> 

3

<<<<Play around with the basic signal processing>>>>

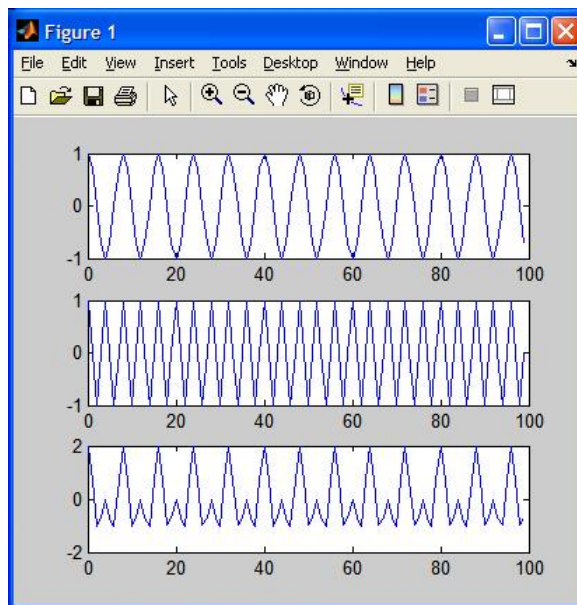
```
x0(1:2000)=cos(2*pi*1000*((1:2000)-1)/8000); - generate 1000Hz signal
sound(x0,8000); - create sound of the above signal
subplot(311),plot((1:100)-1,x0(1:100)); - plot the signal
```

-another frequency

```
x1(1:2000)=cos(2*pi*2000*((1:2000)-1)/8000); - generate 2000Hz signal
sound(x1,8000); - create sound of the above signal
subplot(312),plot((1:100)-1,x1(1:100)); - plot the signal
```

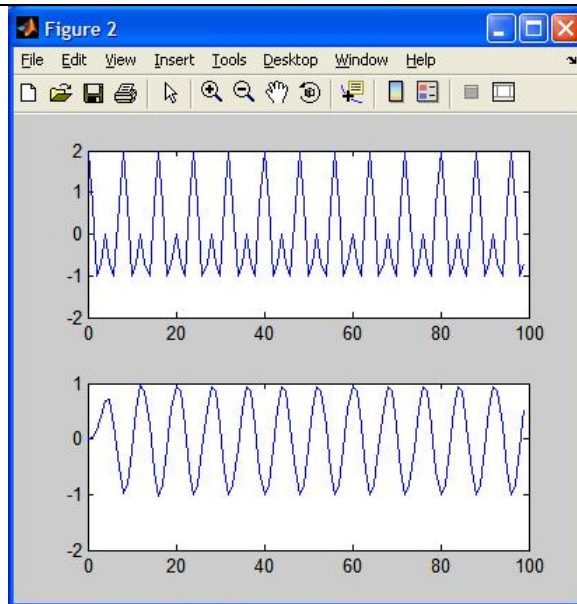
-combination of both signals (in time domain)

```
x2=x0+x1;
sound(x2,8000);
subplot(313),plot((1:100)-1,x2(1:100));
```



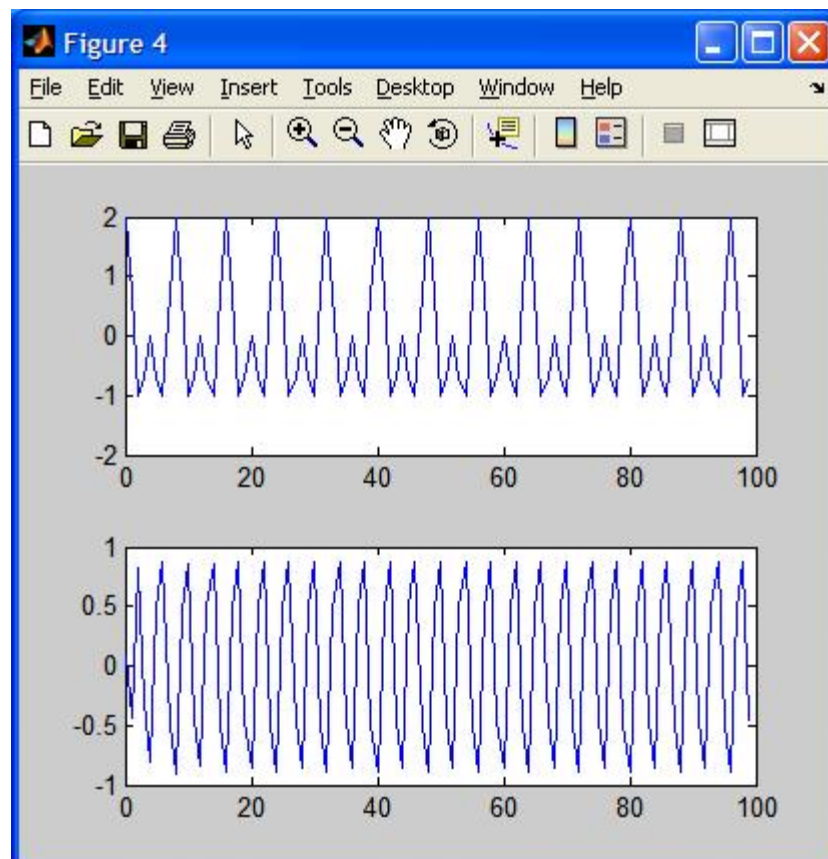
-introduce an IIR Butterworth filter for filtering signal x2 with a 1500Hz low-pass filter

```
[b0,a0]= butter(8,1500/4000);
y0=filter(b0,a0,x2);
subplot(211),plot((1:100)-1,x2(1:100)); - before low pass filter
subplot(212),plot((1:100)-1,y0(1:100)); - after low pass filter
```

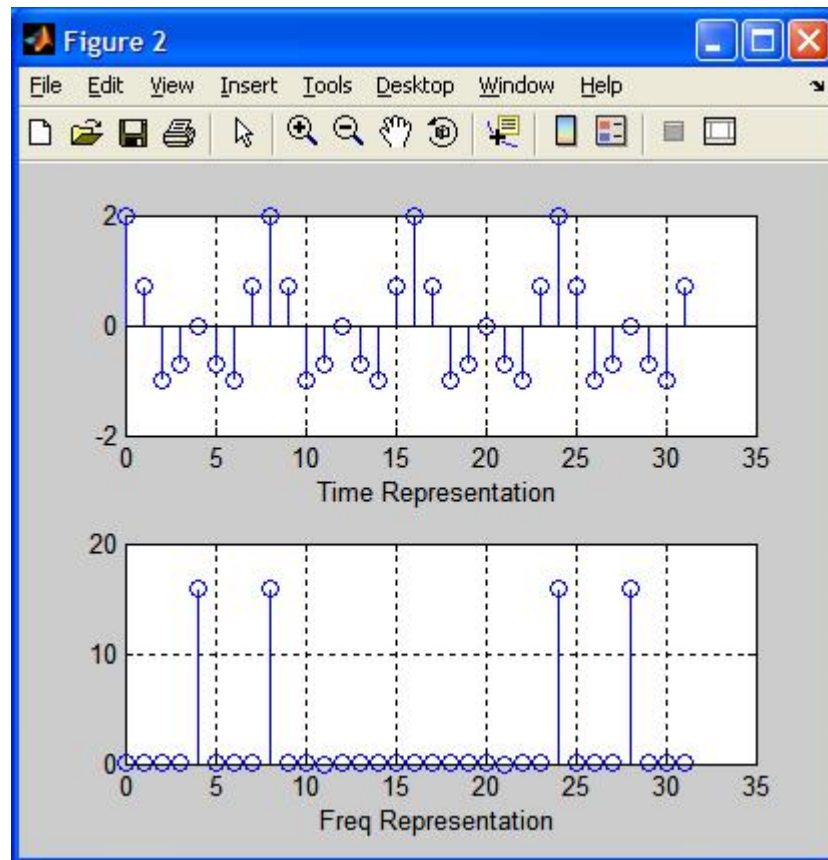


-introduce an IIR Butterworth filter for filtering signal x2 with 1500Hz high-pass filter

```
[b1,a1]= butter(8,1500/4000,'high');
y1=filter(b1,a1,x2);
subplot(211),plot((1:100)-1,x2(1:100)); -
subplot(212),plot((1:100)-1,y1(1:100));
```



```
X(1:32)=abs(fft(x2(1:32)));
subplot(211),stem((1:32)-1,x2(1:32));xlabel('Time Representation');grid
subplot(212),stem((1:32)-1,X(1:32));xlabel('Freq Representation');grid
```

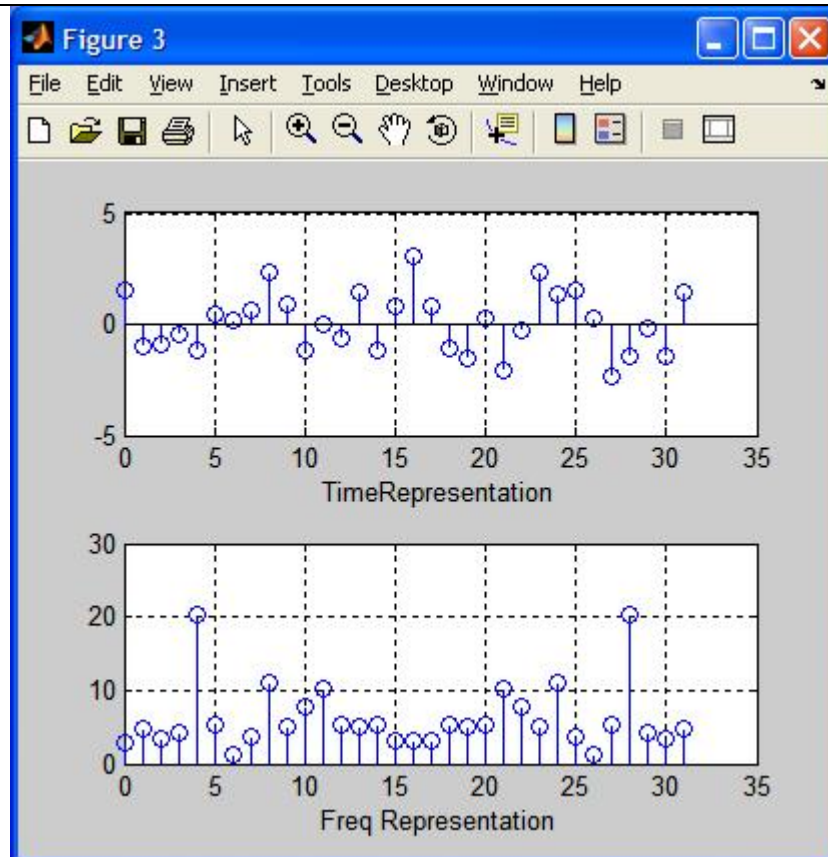


This graph is based on 32 points. Take half of the points, $N=16$. For point 0 to 15, the signal is the True Spectrum. For point 16 to 32, the signal is the replicated signal.

From the FFT graph, we can actually determine the frequency of the signal rather than determine the frequency of the signal using time domain ($F_s=1/T_s$). The signals can be a combination of multiple frequency signals.

Lets introduce some noise:

```
n=randn(1,2000);
x3=x2+n;
X3(1:32)=abs(fft(x3(1:32)));
figure; subplot(211),stem((1:32)-1,x3(1:32));xlabel('TimeRepresentation');grid
subplot(212),stem((1:32)-1,X3(1:32));xlabel('Freq Representation');grid
```



From the FFT graph, we still can distinguish the frequencies compared to visualize it in time domain.

*MATLAB request any filtration must be done in time domain but the design stage must be in frequency domain (for DSP cases)

5 Hands-on DSP Board (C5416)

File: "InOutCodec" – input from signal generator and send out a signal

File: "IIRasgenerator" – DSP as signal generator, creating sinusoidal signal

File: "IIRfilter" – to test IIR filter upon a given sinusoid input

File: "FIRfilter" – to test FIR filter upon a given sinusoid input

:Unfortunately, the DSK board only support up to 25 order. Any FIR filter with order higher than 25, the resulting output will be distorted. This is due to higher order system, the DSP needs to calculate longer mathematical equation.

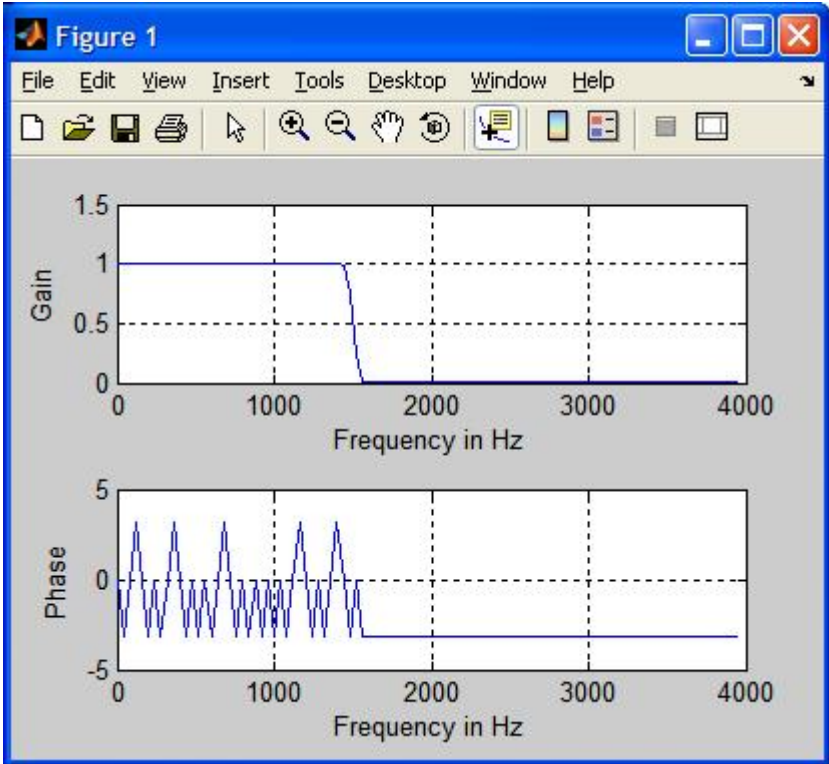
FIR is suitable if the system can works with delays. Otherwise, IIR is recommended.

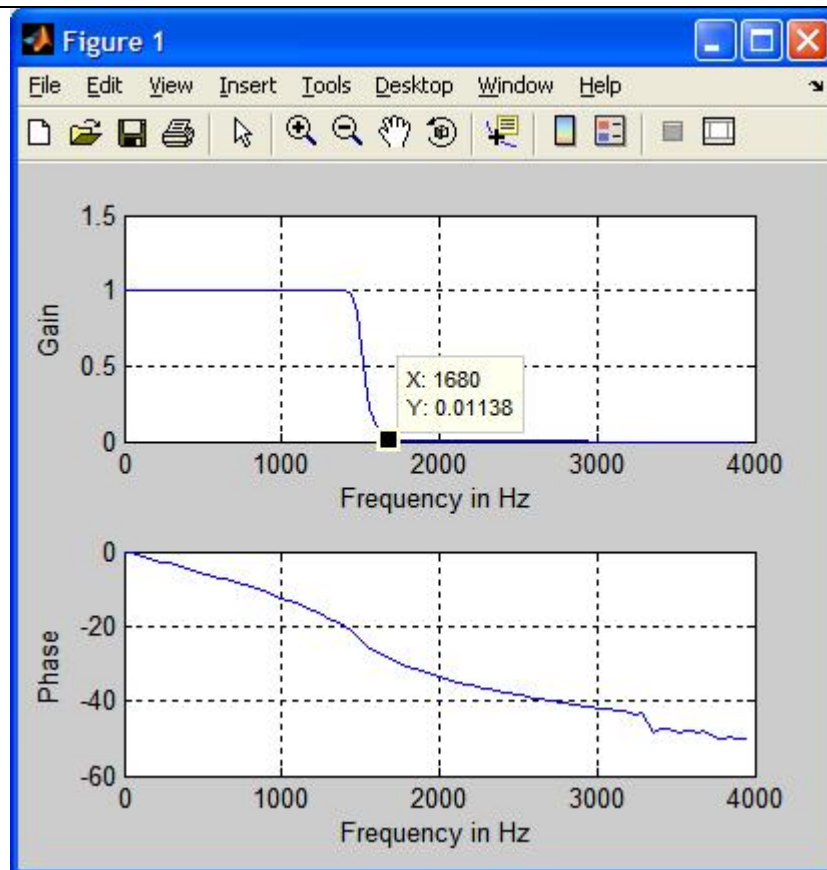
-to find an unknown filter cut-off frequency, check the output response, tune input until output is 0.7071V @ 1.414Vp-p (3dB point)!

6 Case-Studies:

-read file *.wave using matlab
y0=wavread('y0.wav')

-write file *.wave using matlab
wavwrite(y1f,'c:\Y1f.wav');

No.	Problems
1a	<p>Design a low-pass filter with the following specifications: $F_s=8000\text{Hz}$, $f_{CL}=1500\text{Hz}$, Transition Band $<200\text{Hz}$</p> <p>Solutions:</p> <pre>[b]= fir1(200,[1500]/4000,'low'); zplane(b,1); [h,f]=freqz(b,1,100,8000); subplot(211),plot(f,abs(h));grid;xlabel('Frequency in Hz');ylabel('Gain'); subplot(212),plot(f,unwrap(angle(h)));grid;xlabel('Frequency in Hz');ylabel('Phase');</pre>  <p>The figure displays two subplots within a MATLAB window titled 'Figure 1'. The top subplot shows the magnitude response (Gain) versus Frequency in Hz. The gain is constant at 1.0 for frequencies below 1500 Hz and then drops sharply to 0.0 by 1700 Hz. The bottom subplot shows the phase response (Phase) versus Frequency in Hz. The phase is constant at 0 for frequencies below 1500 Hz and then drops sharply to -pi (approximately -3.14) by 1700 Hz. Both plots have a grid and are labeled with 'Frequency in Hz' on the x-axis.</p>
1b	<pre>[b,a]= butter(30,[1500]/4000,'low'); [h,f]=freqz(b,a,100,8000); subplot(211),plot(f,abs(h));grid;xlabel('Frequency in Hz');ylabel('Gain'); subplot(212),plot(f,unwrap(angle(h)));grid;xlabel('Frequency in Hz');ylabel('Phase');</pre>



1c

```
[b,a]=cheby1(8,0.75,1500/4000);
[h,f]=freqz(b,a,100,8000);
subplot(211),plot(f,abs(h));grid;xlabel('Frequency in Hz');ylabel('Gain');
subplot(212),plot(f,unwrap(angle(h)));grid;xlabel('Frequency in Hz');ylabel('Phase');
```

